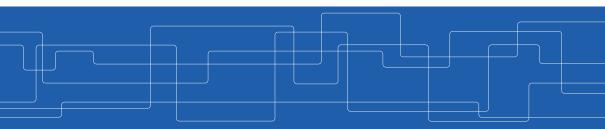


Introduction

Amir H. Payberah payberah@kth.se 30/10/2018





Course Information



- ► This course has a system-based focus
- Learn the theory of machine learning and deep learning
- Learn the practical aspects of building machine learning and deep learning algorithms using data parallel programming platforms, such as Spark and TensorFlow



► Part 1: large scale machine learning

► Part 2: large scale deep learning



Topics of Study

► Part 1: large scale machine learning

- Spark ML
- Linear regression and logistic regression
- Decision tree and ensemble models
- ► Part 2: large scale deep learning



Topics of Study

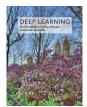
Part 1: large scale machine learning

- Spark ML
- Linear regression and logistic regression
- Decision tree and ensemble models
- ► Part 2: large scale deep learning
 - TensorFlow
 - Deep feedforward networks
 - Convolutional neural networks (CNNs)
 - Recurrent neural networks (RNNs)
 - Autoencoders and Restricted Boltzmann machines (RBMs)



The Course Material

- ► Deep learning, I. Goodfellow et al., Cambridge: MIT press, 2016
- Hands-on machine learning with Scikit-Learn and TensorFlow, A. Geron, O'Reilly Media, 2017
- Spark The Definitive Guide, M. Zaharia et al., O'Reilly Media, 2018.









The Course Grading

- ► Two lab assignments: 30%
- ► One final project: 20%
- ► Eight review questions: 20%
- ► The final exam: 30%



The Labs and Project

- Self-selected groups of two
- Labs
 - Include Scala/Python programming
 - Lab1: Regression using Spark ML
 - Lab2: Deep neural network and CNN using Tensorflow

Project

- Selection of a large dataset and method
- RNNs, Autoencoders, or RBMs
- Demonstrated as a demo and short report



The Course Web Page

https://id2223kth.github.io



The Course Overview



Sheepdog or Mop





Chihuahua or Muffin





Barn Owl or Apple





Raw Chicken or Donald Trump





Artificial Intelligence Challenge

 Artificial intelligence (AI) can solve problems that can be described by a list of formal mathematical rules.



Artificial Intelligence Challenge

- Artificial intelligence (AI) can solve problems that can be described by a list of formal mathematical rules.
- ► The challenge is to solve the tasks that are hard for people to describe formally.



Artificial Intelligence Challenge

- Artificial intelligence (AI) can solve problems that can be described by a list of formal mathematical rules.
- ► The challenge is to solve the tasks that are hard for people to describe formally.
- Let computers to learn from experience.



History of AI



▶ Hephaestus, the god of blacksmith, created a metal automaton, called Talos.





[the left figure: http://mythologian.net/hephaestus-the-blacksmith-of-gods] [the right figure: http://elderscrolls.wikia.com/wiki/Talos]



1920: Rossum's Universal Robots (R.U.R.)

- ► A science fiction play by Karel Čapek, in 1920.
- A factory that creates artificial people named robots.

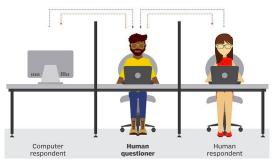


[https://dev.to/lschultebraucks/a-short-history-of-artificial-intelligence-7hm]



1950: Turing Test

- ► In 1950, Turing introduced the Turing test.
- An attempt to define machine intelligence.



[https://searchenterpriseai.techtarget.com/definition/Turing-test]



1956: The Dartmouth Workshop

- Probably the first workshop of AI.
- ▶ Researchers from CMU, MIT, IBM met together and founded the AI research.

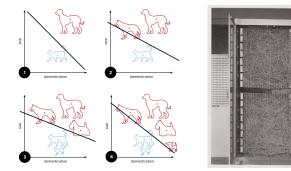


[https://twitter.com/lordsaicom/status/898139880441696257]



1958: Perceptron

- A supervised learning algorithm for binary classifiers.
- ▶ Implemented in custom-built hardware as the Mark 1 perceptron.

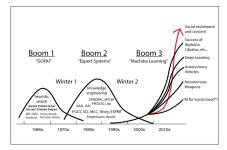


[https://en.wikipedia.org/wiki/Perceptron]



1974-1980: The First Al Winter

- ▶ The over optimistic settings, which were not occurred
- ► The problems:
 - Limited computer power
 - Lack of data
 - Intractability and the combinatorial explosion

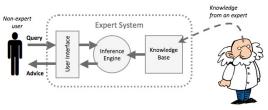


[[]http://www.technologystories.org/ai-evolution]



1980's: Expert systems

- ► The programs that solve problems in a specific domain.
- ► Two engines:
 - Knowledge engine: represents the facts and rules about a specific topic.
 - Inference engine: applies the facts and rules from the knowledge engine to new facts.

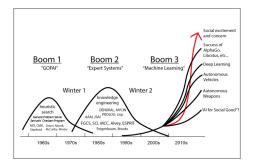


[https://www.igcseict.info/theory/7_2/expert]



1987-1993: The Second Al Winter

- After a series of financial setbacks.
- ▶ The fall of expert systems and hardware companies.



[http://www.technologystories.org/ai-evolution]



► The first chess computer to beat a world chess champion Garry Kasparov.



[http://marksist.org/icerik/Tarihte-Bugun/1757/11-Mayis-1997-Deep-Blue-adli-bilgisayar]



2012: AlexNet - Image Recognition

- ► The ImageNet competition in image classification.
- The AlexNet Convolutional Neural Network (CNN) won the challenge by a large margin.

IM GENET



2016: DeepMind AlphaGo

- ► DeepMind AlphaGo won Lee Sedol, one of the best players at Go.
- ► In 2017, DeepMind published AlphaGo Zero.
 - The next generation of AlphaGo.
 - It learned Go by playing against itself.



[https://www.zdnet.com/article/google-alphago-caps-victory-by-winning-final-historic-go-match]



2018: Google Duplex

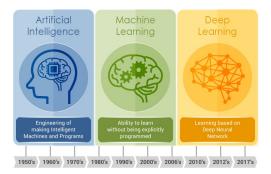
- ► An AI system for accomplishing real-world tasks over the phone.
- ► A Recurrent Neural Network (RNN) built using TensorFlow.





AI Generations

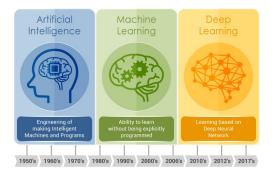
- Rule-based AI
- Machine learning
- Deep learning





Al Generations - Rule-based Al

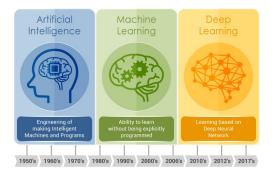
- Hard-code knowledge
- Computers reason using logical inference rules





Al Generations - Machine Learning

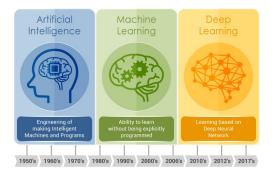
- If AI systems acquire their own knowledge
- Learn from data without being explicitly programmed





Al Generations - Deep Learning

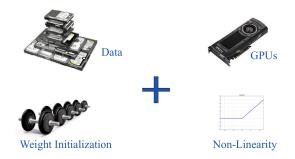
- ► For many tasks, it is difficult to know what features should be extracted
- ► Use machine learning to discover the mapping from representation to output





Why Does Deep Learning Work Now?

- Huge quantity of data
- Tremendous increase in computing power
- Better training algorithms





Machine Learning and Deep Learning





Learning Algorithms

- A ML algorithm is an algorithm that is able to learn from data.
- ► What is learning?



Learning Algorithms

- A ML algorithm is an algorithm that is able to learn from data.
- ► What is learning?
- A computer program is said to learn from experience E with respect to some class of tasks T and performance measure P, if its performance at tasks in T, as measured by P, improves with experience E. (Tom M. Mitchell)





A spam filter that can learn to flag spam given examples of spam emails and examples of regular emails.



[https://bit.ly/20iplYM]



- A spam filter that can learn to flag spam given examples of spam emails and examples of regular emails.
- ► Task T: flag spam for new emails
- Experience E: the training data
- ▶ Performance measure P: the ratio of correctly classified emails



[https://bit.ly/20iplYM]



Given dataset of prices of 500 houses, how can we learn to predict the prices of other houses, as a function of the size of their living areas?



[https://bit.ly/2MyiJUy]



- Given dataset of prices of 500 houses, how can we learn to predict the prices of other houses, as a function of the size of their living areas?
- ► Task T: predict the price
- Experience E: the dataset of living areas and prices
- ► Performance measure P: the difference between the predicted price and the real price



[https://bit.ly/2MyiJUy]



Types of Machine Learning Algorithms

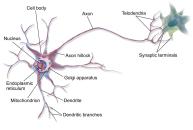
- Supervised learning
 - Input data is labeled, e.g., spam/not-spam or a stock price at a time.
 - Regression vs. classification
- Unsupervised learning
 - Input data is unlabeled.
 - Find hidden structures in data.





From Machine Learning to Deep Learning

- ▶ Deep Learning (DL) is part of ML methods based on learning data representations.
- Mimic the neural networks of our brain.



[A. Geron, O'Reilly Media, 2017]



Artificial Neural Networks

► Artificial Neural Network (ANN) is inspired by biological neurons.



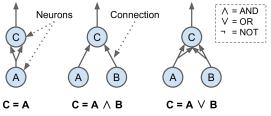
Artificial Neural Networks

- ► Artificial Neural Network (ANN) is inspired by biological neurons.
- One or more binary inputs and one binary output
- Activates its output when more than a certain number of its inputs are active.



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The Linear Threshold Unit (LTU)

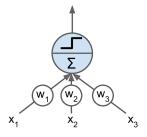
► Inputs of a LTU are numbers (not binary).



The Linear Threshold Unit (LTU)

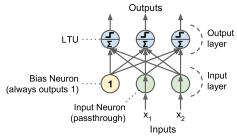
- ► Inputs of a LTU are numbers (not binary).
- Each input connection is associated with a weight.
- Computes a weighted sum of its inputs and applies a step function to that sum.

- $\blacktriangleright z = w_1 x_1 + w_2 x_2 + \dots + w_n x_n = \mathbf{w}^\mathsf{T} \mathbf{x}$
- $\hat{y} = \text{step}(z) = \text{step}(w^T x)$





- The perceptron is a single layer of LTUs.
- ► The input neurons output whatever input they are fed.
- ► A bias neuron, which just outputs 1 all the time.





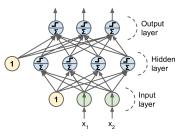
Deep Learning Models

- Deep Neural Network (DNN)
- Convolutional Neural Network (CNN)
- Recurrent Neural Network (RNN)
- Autoencoders



Deep Neural Networks

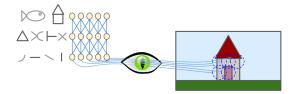
- Multi-Layer Perceptron (MLP)
 - One input layer
 - One or more layers of LTUs (hidden layers)
 - One final layer of LTUs (output layer)
- ▶ Deep Neural Network (DNN) is an ANN with two or more hidden layers.
- Backpropagation training algorithm





Convolutional Neural Networks

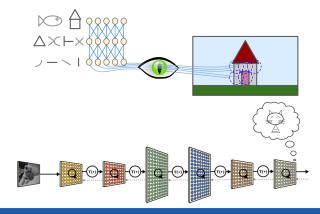
▶ Many neurons in the visual cortex react only to a limited region of the visual field.





Convolutional Neural Networks

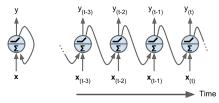
- ▶ Many neurons in the visual cortex react only to a limited region of the visual field.
- ► The higher-level neurons are based on the outputs of neighboring lower-level neurons





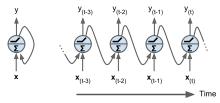
Recurrent Neural Networks

► The output depends on the input and the previous computations.





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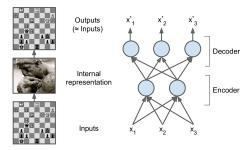
Analyze time series data, e.g., stock market, and autonomous driving systems

▶ Work on sequences of arbitrary lengths, rather than on fixed-sized inputs





- ► Learn efficient representations of the input data, without any supervision.
 - With a lower dimensionality than the input data
- Generative model: generate new data that looks very similar to the training data.
- Preserve as much information as possible



[A. Geron, O'Reilly Media, 2017]



Linear Algebra Review





- A vector is an array of numbers.
- ► Notation:
 - Denoted by **bold** lowercase letters, e.g., **x**.
 - $\textbf{x}_{\texttt{i}}$ denotes the <code>ith</code> entry.

$$\mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}$$



Matrix and Tensor

- A matrix is a 2-D array of numbers.
- A tensor is an array with more than two axes.
- Notation:
 - Denoted by **bold** uppercase letters, e.g., **A**.
 - a_{ij} denotes the entry in ith row and jth column.
 - If A is $m \times n$, it has m rows and n columns.

$$\mathbf{A} = \begin{bmatrix} a_{1,1} & a_{1,2} & a_{1,3} & \dots & a_{1,n} \\ a_{2,1} & a_{2,2} & a_{2,3} & \dots & a_{2,n} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ a_{m,1} & a_{m,2} & a_{m,3} & \dots & a_{m,n} \end{bmatrix}$$



Matrix Addition and Subtraction

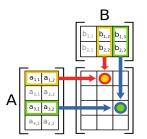
► The matrices must have the same dimensions.

$$\mathbf{A} = \begin{bmatrix} a & b \\ c & d \end{bmatrix} + \begin{bmatrix} e & f \\ g & h \end{bmatrix} = \begin{bmatrix} a+e & b+f \\ c+g & d+h \end{bmatrix}$$



- Matrix Product
- The matrix product of matrices A and B is a third matrix C, where C = AB.
- If **A** is of shape $m \times n$ and **B** is of shape $n \times p$, then **C** is of shape $m \times p$.

$$c_{ij} = \sum_k a_{ik} b_{kj}$$



[https://en.wikipedia.org/wiki/Matrix_multiplication]

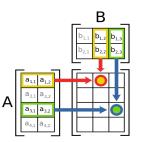


Matrix Product

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$$c_{ij} = \sum_k a_{ik} b_{kj}$$

- Properties
 - Associative: (AB)C = A(BC)
 - Not commutative: $AB \neq BA$



[https://en.wikipedia.org/wiki/Matrix_multiplication]



• Swap the rows and columns of a matrix.

$$\mathbf{A} = \begin{bmatrix} a & b \\ c & d \\ e & \mathbf{f} \end{bmatrix} \Rightarrow \mathbf{A}^{\mathsf{T}} = \begin{bmatrix} a & c & e \\ b & d & \mathbf{f} \end{bmatrix}$$



Matrix Transpose

Swap the rows and columns of a matrix.

$$\mathbf{A} = \begin{bmatrix} a & b \\ c & d \\ e & f \end{bmatrix} \Rightarrow \mathbf{A}^{\mathsf{T}} = \begin{bmatrix} a & c & e \\ b & d & f \end{bmatrix}$$

- Properties
 - $\mathbf{A}_{ij} = \mathbf{A}_{ji}^{\mathsf{T}}$
 - If **A** is $m \times n$, then **A**^T is $n \times m$
 - $(A + B)^{T} = A^{T} + B^{T}$
 - $(\mathbf{A}\mathbf{B})^{\mathsf{T}} = \mathbf{B}^{\mathsf{T}}\mathbf{A}^{\mathsf{T}}$



Inverse of a Matrix

• If **A** is a square matrix, its inverse is called A^{-1} .

 $AA^{-1} = A^{-1}A = I$

▶ Where I, the identity matrix, is a diagonal matrix with all 1's on the diagonal.

$$\mathbf{I}_2 = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \qquad \mathbf{I}_3 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$



$L^p\ \mbox{Norm}$ for Vectors

- We can measure the size of vectors using a norm function.
- ► Norms are functions mapping vectors to non-negative values.
- ► L¹ norm

$$\|\mathbf{x}\|_1 = \sum_i |\mathbf{x}_i|$$



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$$\|\mathbf{x}\|_1 = \sum_{i} |\mathbf{x}_i|$$

$$||\mathbf{x}||_2 = (\sum_i |\mathbf{x}_i|^2)^{\frac{1}{2}} = \sqrt{\mathbf{x}_1^2 + \mathbf{x}_2^2 + \dots + \mathbf{x}_n^2}$$



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$$L^2$$
 norm
$$||\bm{x}||_2 = (\sum_i |x_i|^2)^{\frac{1}{2}} = \sqrt{x_1^2 + x_2^2 + \dots + x_n^2}$$

▶ L^p norm

$$||\textbf{x}||_p = (\sum_{\texttt{i}} |\texttt{x}_{\texttt{i}}|^p)^{\frac{1}{p}}$$



Probability Review



Random Variables

- ▶ Random variable: a variable that can take on different values randomly.
- Random variables may be discrete or continuous.
 - Discrete random variable: finite or countably infinite number of states
 - Continuous random variable: real value



- ▶ Random variable: a variable that can take on different values randomly.
- ► Random variables may be discrete or continuous.
 - Discrete random variable: finite or countably infinite number of states
 - Continuous random variable: real value
- Notation:
 - Denoted by an upper case letter, e.g., X
 - Values of a random variable X are denoted by lower case letters, e.g., x and y.



Probability Distributions

- Probability distribution: how likely a random variable is to take on each of its possible states.
 - E.g., the random variable ${\tt X}$ denotes the outcome of a coin toss.
 - The probability distribution of X would take the value 0.5 for X = head, and 0.5 for Y = tail (assuming the coin is fair).



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 - The probability distribution of X would take the value 0.5 for X = head, and 0.5 for Y = tail (assuming the coin is fair).
- The way we describe probability distributions depends on whether the variables are discrete or continuous.



Discrete Variables

- Probability mass function (PMF): the probability distribution of a discrete random variable X.
- Notation: denoted by a lowercase p.
 - E.g., p(x) = 1 indicates that X = x is certain
 - E.g., p(x) = 0 indicates that X = x is impossible



Discrete Variables

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- Notation: denoted by a lowercase p.
 - E.g., p(x) = 1 indicates that X = x is certain
 - E.g., p(x) = 0 indicates that X = x is impossible
- Properties:
 - The domain D of p must be the set of all possible states of ${\tt X}$
 - $\forall x \in D(X), 0 \le p(x) \le 1$
 - $\sum_{x \in D(X)} p(x) = 1$



Two random variables X and Y are independent, if their probability distribution can be expressed as their products.

 $\forall \mathtt{x} \in \mathtt{D}(\mathtt{X}), \mathtt{y} \in \mathtt{D}(\mathtt{Y}), \mathtt{p}(\mathtt{X} = \mathtt{x}, \mathtt{Y} = \mathtt{y}) = \mathtt{p}(\mathtt{X} = \mathtt{x})\mathtt{p}(\mathtt{Y} = \mathtt{y})$



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► E.g., if a coin is tossed and a single 6-sided die is rolled, then the probability of landing on the head side of the coin and rolling a 3 on the die is:



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► E.g., if a coin is tossed and a single 6-sided die is rolled, then the probability of landing on the head side of the coin and rolling a 3 on the die is:

$$\mathtt{p}(\mathtt{X}=\mathtt{head},\mathtt{Y}=\mathtt{3})=\mathtt{p}(\mathtt{X}=\mathtt{head})\mathtt{p}(\mathtt{Y}=\mathtt{3})=\frac{1}{2}\times\frac{1}{6}=\frac{1}{12}$$



Conditional Probability

Conditional probability: the probability of an event given that another event has occurred.

$$p(Y = y \mid X = x) = \frac{p(Y = y, X = x)}{p(X = x)}$$



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► E.g., if 60% of the class passed both labs and 80% of the class passed the first labs, then what percent of those who passed the first lab also passed the second lab?



Conditional Probability

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$$p(Y = y \mid X = x) = \frac{p(Y = y, X = x)}{p(X = x)}$$

- ► E.g., if 60% of the class passed both labs and 80% of the class passed the first labs, then what percent of those who passed the first lab also passed the second lab?
 - E.g., X and Y random variables for the first and the second labs, respectively.

$$p(Y = \texttt{lab2} \mid \texttt{X} = \texttt{lab1}) = \frac{p(Y = \texttt{lab2}, \texttt{X} = \texttt{lab1})}{p(\texttt{X} = \texttt{lab1})} = \frac{0.6}{0.8} = \frac{3}{4}$$



The expected value of a random variable X with respect to a probability distribution p(X) is the average value that X takes on when it is drawn from p(X).

$$\mathbf{E}_{\mathbf{x}\sim \mathbf{p}}[\mathbf{X}] = \sum_{\mathbf{x}} \mathbf{p}(\mathbf{x})\mathbf{x}$$



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• E.g., If $X : \{1, 2, 3\}$, and p(X = 1) = 0.3, p(X = 2) = 0.5, p(X = 3) = 0.2



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▶ E.g., If X : {1,2,3}, and p(X = 1) = 0.3, p(X = 2) = 0.5, p(X = 3) = 0.2• $E[X] = 0.3 \times 1 + 0.5 \times 2 + 0.2 \times 3 = 1.9$



► The variance gives a measure of how much the values of a random variable X vary as we sample it from its probability distribution p(X).

$$ext{Var}(\mathtt{X}) = \mathtt{E}[(\mathtt{X} - \mathtt{E}[\mathtt{X}])^2]$$
 $ext{Var}(\mathtt{X}) = \sum_{\mathtt{x}} \mathtt{p}(\mathtt{x})(\mathtt{x} - \mathtt{E}[\mathtt{X}])^2$



► The variance gives a measure of how much the values of a random variable X vary as we sample it from its probability distribution p(X).

$$ext{Var}(ext{X}) = ext{E}[(ext{X} - ext{E}[ext{X}])^2] \ ext{Var}(ext{X}) = \sum_{ ext{x}} ext{p}(ext{x})(ext{x} - ext{E}[ext{X}])^2 \ ext{Var}(ext{X}) = \sum_{ ext{x}} ext{p}(ext{x})(ext{x} - ext{E}[ext{X}])^2 \ ext{Var}(ext{X}) = \sum_{ ext{x}} ext{p}(ext{x})(ext{x} - ext{E}[ext{X}])^2 \ ext{Var}(ext{X}) = \sum_{ ext{x}} ext{p}(ext{x})(ext{x} - ext{E}[ext{X}])^2 \ ext{Var}(ext{X}) = \sum_{ ext{x}} ext{p}(ext{x})(ext{x} - ext{E}[ext{X}])^2 \ ext{Var}(ext{X}) = \sum_{ ext{x}} ext{p}(ext{x})(ext{x} - ext{E}[ext{X}])^2 \ ext{Var}(ext{X}) = \sum_{ ext{x}} ext{p}(ext{x})(ext{x} - ext{E}[ext{X}])^2 \ ext{Var}(ext{x}) = \sum_{ ext{x}} ext{p}(ext{x})(ext{x} - ext{E}[ext{X}])^2 \ ext{Var}(ext{x}) = \sum_{ ext{x}} ext{p}(ext{x})(ext{x} - ext{E}[ext{X}])^2 \ ext{Var}(ext{x}) = \sum_{ ext{x}} ext{p}(ext{x})(ext{x} - ext{E}[ext{x}])^2 \ ext{var}(ext{x}) = \sum_{ ext{x}} ext{p}(ext{x})(ext{x} - ext{E}[ext{x}])^2 \ ext{var}(ext{x}) = \sum_{ ext{x}} ext{p}(ext{x})(ext{x})(ext{x} - ext{E}[ext{x}])^2 \ ext{var}(ext{x}) = \sum_{ ext{x}} ext{p}(ext{x})(e$$

• E.g., If $X : \{1, 2, 3\}$, and p(X = 1) = 0.3, p(X = 2) = 0.5, p(X = 3) = 0.2



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- ▶ E.g., If $X : \{1, 2, 3\}$, and p(X = 1) = 0.3, p(X = 2) = 0.5, p(X = 3) = 0.2
 - $E[X] = 0.3 \times 1 + 0.5 \times 2 + 0.2 \times 3 = 1.9$
 - $Var(X) = 0.3(1 1.9)^2 + 0.5(2 1.9)^2 + 0.2(3 1.9)^2 = 0.49$



► The variance gives a measure of how much the values of a random variable X vary as we sample it from its probability distribution p(X).

$$ext{Var}(X) = ext{E}[(X - ext{E}[X])^2]$$
 $ext{Var}(X) = \sum_{x} p(x)(x - ext{E}[X])^2$

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- The standard deviation, shown by σ , is the square root of the variance.



Covariance (1/2)

The covariance gives some sense of how much two values are linearly related to each other.

$$\begin{aligned} \mathtt{Cov}(\mathtt{X},\mathtt{Y}) &= \mathtt{E}[(\mathtt{X}-\mathtt{E}[\mathtt{X}])(\mathtt{Y}-\mathtt{E}[\mathtt{Y}])]\\ \mathtt{Cov}(\mathtt{X},\mathtt{Y}) &= \sum \sum_{(\mathtt{x},\mathtt{y})} \mathtt{p}(\mathtt{x},\mathtt{y})(\mathtt{x}-\mathtt{E}[\mathtt{X}])(\mathtt{y}-\mathtt{E}[\mathtt{Y}]) \end{aligned}$$

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Covariance (2/2)

			Y		
	p(X, Y)	1	2	3	p(X)
	1	1/4	1/4	0	1/2
Х	2	0	1/4	1/4	1/2
	p(Y)	1/4	1/2	1/4	1

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$$E[X] = \frac{1}{2} \times 1 + \frac{1}{2} \times 2 = \frac{3}{2}$$
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KTH VETENSKAP OCH KONST

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$$\begin{split} E[X] &= \frac{1}{2} \times 1 + \frac{1}{2} \times 2 = \frac{3}{2} \qquad E[Y] = \frac{1}{4} \times 1 + \frac{1}{2} \times 2 + \frac{1}{4} \times 3 = 2 \\ Cov(X, Y) &= \sum \sum_{(x,y)} p(x, y)(x - E[X])(y - E[Y]) \end{split}$$

KTH VETENSKAP OCH KONST

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			Y		
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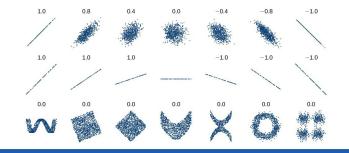
$$E[X] = \frac{1}{2} \times 1 + \frac{1}{2} \times 2 = \frac{3}{2} \qquad E[Y] = \frac{1}{4} \times 1 + \frac{1}{2} \times 2 + \frac{1}{4} \times 3 = 2$$
$$Cov(X, Y) = \sum \sum_{(x,y)} p(x, y)(x - E[X])(y - E[Y])$$
$$= \frac{1}{4}(1 - \frac{3}{2})(1 - 2) + \frac{1}{4}(1 - \frac{3}{2})(2 - 2) + 0(1 - \frac{3}{2})(3 - 2) +$$
$$= 0(2 - \frac{3}{2})(1 - 2) + \frac{1}{4}(2 - \frac{3}{2})(2 - 2) + \frac{1}{4}(2 - \frac{3}{2})(3 - 2) = \frac{1}{4}$$



Correlation Coefficient

► The Correlation coefficient is a quantity that measures the strength of the association (or dependence) between two random variables, e.g., X and Y.

$$ho(\mathtt{X}, \mathtt{Y}) = rac{\mathtt{Cov}(\mathtt{X}, \mathtt{Y})}{\sigma(\mathtt{X})\sigma(\mathtt{Y})}$$





 Let X : {x⁽¹⁾, x⁽²⁾, · · · , x^(m)} be a discrete random variable drawn independently from a distribution probability p depending on a parameter θ.



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 - For six tosses of a coin, X : {h,t,t,h,t}, h: head, and t: tail.
 - Suppose you have a coin with probability θ to land heads and (1θ) to land tails.



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• $p(X \mid \theta = \frac{2}{3})$ is the probability of X given $\theta = \frac{2}{3}$.



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- $p(X = h | \theta)$ is the likelihood of θ given X = h.



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 - Suppose you have a coin with probability θ to land heads and (1θ) to land tails.
- $p(X \mid \theta = \frac{2}{3})$ is the probability of X given $\theta = \frac{2}{3}$.
- $p(X = h | \theta)$ is the likelihood of θ given X = h.
- Likelihood (L): a function of the parameters (θ) of a probability model, given specific observed data, e.g., X = h.

$$L(\theta \mid X) = p(X \mid \theta)$$



- ► The likelihood differs from that of a probability.
- A probability $p(X | \theta)$ refers to the occurrence of future events.
- ► A likelihood $L(\theta \mid X)$ refers to past events with known outcomes.



Maximum Likelihood Estimator

► If samples in X are independent we have:

$$\begin{split} \mathsf{L}(\theta \mid \mathsf{X}) &= \mathsf{p}(\mathsf{X} \mid \theta) = \mathsf{p}(\mathsf{x}^{(1)}, \mathsf{x}^{(2)}, \cdots, \mathsf{x}^{(\mathsf{m})} \mid \theta) \\ &= \mathsf{p}(\mathsf{x}^{(1)} \mid \theta) \mathsf{p}(\mathsf{x}^{(2)} \mid \theta) \cdots \mathsf{p}(\mathsf{x}^{(\mathsf{m})} \mid \theta) = \prod_{i=1}^{\mathsf{m}} \mathsf{p}(\mathsf{x}^{(i)} \mid \theta) \end{split}$$



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The maximum likelihood estimator (MLE): what is the most likely value of θ given the training set?

$$\widehat{\theta}_{\texttt{MLE}} = \arg\max_{\theta} \texttt{L}(\theta \mid \texttt{X}) = \arg\max_{\theta} \prod_{\texttt{i}=1}^{\texttt{m}} \texttt{p}(\texttt{x}^{\texttt{(i)}} \mid \theta)$$



Maximum Likelihood Estimator - Example

- Six tosses of a coin, with the following model:
 - Possible outcomes: h with probability of θ , and t with probability (1θ) .
 - Results of coin tosses are independent of one another.
- ▶ Data: $X : \{h, t, t, t, h, t\}$



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- The likelihood is

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• $\hat{\theta}$ is the value of θ that maximizes the likelihood:

$$\widehat{ heta}_{ extsf{MLE}} = rg\max_{ heta} \mathtt{L}(heta \mid \mathtt{X}) = rac{2}{2+4}$$

0



• The MLE product is prone to numerical underflow.

$$\hat{\theta}_{\texttt{MLE}} = \arg\max_{\theta} \texttt{L}(\theta \mid \texttt{X}) = \arg\max_{\theta} \prod_{\texttt{i}=1}^{\texttt{m}} \texttt{p}(\texttt{x}^{\texttt{(i)}} \mid \theta)$$



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► To overcome this problem we can use the logarithm of the likelihood.

• It does not change its arg max, but transforms a product into a sum.

$$\hat{\theta}_{\texttt{MLE}} = \arg \max_{\theta} \sum_{i=1}^{m} \texttt{logp}(\texttt{x}^{(i)} \mid \theta)$$



• Likelihood: $L(\theta \mid X) = \prod_{i=1}^{m} p(x^{(i)} \mid \theta)$



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- ▶ Negative Log-Likelihood: $-\log L(\theta \mid X) = -\sum_{i=1}^{m} \log (x^{(i)} \mid \theta)$



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- ▶ Negative Log-Likelihood: $-\log L(\theta \mid X) = -\sum_{i=1}^{m} \log (x^{(i)} \mid \theta)$
- Negative log-likelihood is also called the cross-entropy



- ► Coss-entropy: quantify the difference (error) between two probability distributions.
- ► How close is the predicted distribution to the true distribution?

$$\mathtt{H}(\mathtt{p},\mathtt{q}) = -\sum_{\mathtt{x}} \mathtt{p}(\mathtt{x}) \mathtt{log}(\mathtt{q}(\mathtt{x}))$$

▶ Where p is the true distribution, and q the predicted distribution.



Cross-Entropy - Example

- Six tosses of a coin: $X : \{h, t, t, t, h, t\}$
- The true distribution p: $p(h) = \frac{2}{6}$ and $p(t) = \frac{4}{6}$
- The predicted distribution q: h with probability of θ , and t with probability (1θ) .



Cross-Entropy - Example

- Six tosses of a coin: $X : \{h, t, t, t, h, t\}$
- The true distribution p: $p(h) = \frac{2}{6}$ and $p(t) = \frac{4}{6}$
- The predicted distribution q: h with probability of θ , and t with probability (1θ) .
- Likelihood: $\theta^2(1-\theta)^4$
- ▶ Negative log likelihood: $-\log(\theta^2(1-\theta)^4) = -2\log(\theta) 4\log(1-\theta)$
- ► Cross entropy: $H(p,q) = -\sum_{x} p(x) \log(q(x))$ = $-p(h) \log(q(h)) - p(t) \log(q(t)) = -\frac{2}{6} \log(\theta) - \frac{4}{6} \log(1-\theta)$



Summary





- Logic-based AI, Machine Learning, Deep Learning
- Deep Learning models
 - Deep Feed Forward
 - Convolutional Neural Network (CNN)
 - Recurrent Neural Network (RNN)
 - Autoencoders
- Linear algebra and probability
 - Random variables
 - Probability distribution
 - Likelihood
 - Negative log-likelihood and cross-entropy



▶ Ian Goodfellow et al., Deep Learning (Ch. 1, 2, 3)



Questions?

Acknowledgements

Some of the pictures were copied from the book Hands-On Machine Learning with Scikit-Learn and TensorFlow, Aurelien Geron, O'Reilly Media, 2017.