

Machine Learning - Regressions

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The Course Web Page

https://id2223kth.github.io



Where Are We?

Deep Learning				
GAN	RL		Distributed Learning	
CNN	RN	IN	Autoencoder	
Deep Feedforward Network Training Feedforward Network				
TensorFlow				
Machine Learning				
Regression Classification More Supervised Learning				
Spark ML				



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Let's Start with an Example







• Given the dataset of m houses.

Living area	No. of bedrooms	Price
2104	3	400
1600	3	330
2400	3	369
:	:	:
1		1.1



▶ Given the dataset of m houses.

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	•	•

Predict the prices of other houses, as a function of the size of living area and number of bedrooms?



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$$\mathbf{x}^{(1)} = \begin{bmatrix} 2104 \\ 3 \end{bmatrix} \quad \mathbf{y}^{(1)} = 400 \qquad \mathbf{x}^{(2)} = \begin{bmatrix} 1600 \\ 3 \end{bmatrix} \quad \mathbf{y}^{(2)} = 330 \qquad \mathbf{x}^{(3)} = \begin{bmatrix} 2400 \\ 3 \end{bmatrix} \quad \mathbf{y}^{(3)} = 369$$



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$$\mathbf{X} = \begin{bmatrix} \mathbf{x}^{(1)T}\\ \mathbf{x}^{(2)T}\\ \mathbf{x}^{(3)T}\\ \vdots \end{bmatrix} = \begin{bmatrix} 2104 & 3\\ 1600 & 3\\ 2400 & 3\\ \vdots & \vdots \end{bmatrix} \qquad \mathbf{y} = \begin{bmatrix} 400\\ 330\\ 369\\ \vdots\\ \vdots \end{bmatrix}$$



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▶ $\mathbf{x}^{(i)} \in \mathbb{R}^2$: $\mathbf{x}_1^{(i)}$ is the living area, and $\mathbf{x}_2^{(i)}$ is the number of bedrooms of the ith house in the training set.



Living area	No. of bedrooms	Price
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:	÷	÷

- ► Predict the prices of other houses ŷ as a function of the size of their living areas x₁, and number of bedrooms x₂, i.e., ŷ = f(x₁, x₂)
- E.g., what is \hat{y} , if $x_1 = 4000$ and $x_2 = 4$?



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- E.g., what is \hat{y} , if $x_1 = 4000$ and $x_2 = 4$?
- As an initial choice: $\hat{y} = f_w(x) = w_1 x_1 + w_2 x_2$





[http://www.vias.org/science_cartoons/regression.html]



Linear Regression



• Our goal: to build a system that takes input $\mathbf{x} \in \mathbb{R}^n$ and predicts output $\hat{\mathbf{y}} \in \mathbb{R}$.



Linear Regression (1/2)

- Our goal: to build a system that takes input $\mathbf{x} \in \mathbb{R}^n$ and predicts output $\hat{\mathbf{y}} \in \mathbb{R}$.
- In linear regression, the output \hat{y} is a linear function of the input x.

$$\begin{split} \hat{y} = \mathtt{f}_\mathtt{w}(\mathtt{x}) = \mathtt{w}_1 \mathtt{x}_1 + \mathtt{w}_2 \mathtt{x}_2 + \cdots + \mathtt{w}_n \mathtt{x}_n \\ \hat{y} = \mathtt{w}^\mathsf{T} \mathtt{x} \end{split}$$

- $\hat{\mathbf{y}}$: the predicted value
- n: the number of features
- x_i: the ith feature value
- w_i : the jth model parameter ($w \in \mathbb{R}^n$)



• Linear regression often has one additional parameter, called intercept b:



 $\hat{y} = \mathbf{w}^{\mathsf{T}} \mathbf{x} + \mathbf{b}$



Linear regression often has one additional parameter, called intercept b:



 $\hat{\mathbf{y}} = \mathbf{w}^{\mathsf{T}}\mathbf{x} + \mathbf{b}$

► Instead of adding the bias parameter b, we can augment **x** with an extra entry that is always set to 1.

$$\hat{y} = f_w(x) = w_0 x_0 + w_1 x_1 + w_2 x_2 + \dots + w_n x_n$$
, where $x_0 = 1$



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 - $w_i=0:$ the value of the feature $x_i,$ has no effect on the prediction $\hat{y}.$





 $\hat{\mathtt{y}} = \mathtt{f}_\mathtt{w}(\mathtt{x}) = \mathtt{w}_0 \mathtt{x}_0 + \mathtt{w}_1 \mathtt{x}_1 + \mathtt{w}_2 \mathtt{x}_2 + \dots + \mathtt{w}_n \mathtt{x}_n$



How to Learn Model Parameters w?



Linear Regression - Cost Function (1/2)



• One reasonable model should make \hat{y} close to y, at least for the training dataset.



Linear Regression - Cost Function (1/2)



- One reasonable model should make \hat{y} close to y, at least for the training dataset.
- Residual: the difference between the dependent variable y and the predicted value \hat{y} .

$$r^{(i)} = y^{(i)} - \hat{y}^{(i)}$$



Linear Regression - Cost Function (2/2)



► Cost function J(w)

- For each value of the **w**, it measures how close the $\hat{y}^{(i)}$ is to the corresponding $y^{(i)}$.
- We can define J(w) as the mean squared error (MSE):

$$J(\boldsymbol{w}) = \texttt{MSE}(\boldsymbol{w}) = \frac{1}{m} \sum_{i}^{m} (\hat{\boldsymbol{y}}^{(i)} - \boldsymbol{y}^{(i)})^2$$



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$$\begin{split} J(\mathbf{w}) &= \text{MSE}(\mathbf{w}) = \frac{1}{m} \sum_{i}^{m} (\hat{y}^{(i)} - y^{(i)})^2 \\ &= \text{E}[(\hat{y} - y)^2] = \frac{1}{m} ||\hat{y} - y||_2^2 \end{split}$$



How to Learn Model Parameters?

- ▶ We want to choose **w** so as to minimize J(**w**).
- ► Two approaches to find w:
 - Normal equation
 - Gradient descent



Normal Equation



Derivatives and Gradient (1/4)



[https://mathequality.wordpress.com/2012/09/26/derivative-dance-gangnam-style/]



Derivatives and Gradient (2/4)

► The first derivative of f(x), shown as f'(x), shows the slope of the tangent line to the function at the poa x.





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- ▶ $f(x) = x^2 \Rightarrow f'(x) = 2x$
- If f(x) is increasing, then f'(x) > 0





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- If f(x) is increasing, then f'(x) > 0
- If f(x) is decreasing, then f'(x) < 0
- If f(x) is at local minimum/maximum, then f'(x) = 0





Derivatives and Gradient (3/4)

- \blacktriangleright What if a function has multiple arguments, e.g., $f(x_1,x_2,\cdots,x_n)$
- ▶ Partial derivatives: the derivative with respect to a particular argument.
 - $\frac{\partial f}{\partial x_1}$, the derivative with respect to x_1
 - $\frac{\partial f}{\partial x_2}$, the derivative with respect to x_2



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- $\frac{\partial f}{\partial x_i}$: shows how much the function f will change, if we change x_i .



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 - $\frac{\partial f}{\partial x_1}$, the derivative with respect to x_1
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- $\frac{\partial f}{\partial x_i}$: shows how much the function f will change, if we change x_i .
- ► Gradient: the vector of all partial derivatives for a function f.

$$abla_{\mathbf{x}}\mathbf{f}(\mathbf{x}) = egin{bmatrix} rac{\partial f}{\partial \mathbf{x}_1} \ rac{\partial f}{\partial \mathbf{x}_2} \ dots \ rac{\partial f}{\partial \mathbf{x}_n} \end{bmatrix}$$



Derivatives and Gradient (4/4)

• What is the gradient of $f(x_1, x_2, x_3) = x_1 - x_1x_2 + x_3^2$?



Derivatives and Gradient (4/4)

• What is the gradient of $f(x_1, x_2, x_3) = x_1 - x_1x_2 + x_3^2$?

$$\nabla_{\mathbf{x}} \mathbf{f}(\mathbf{x}) = \begin{bmatrix} \frac{\partial}{\partial \mathbf{x}_1} (\mathbf{x}_1 - \mathbf{x}_1 \mathbf{x}_2 + \mathbf{x}_3^2) \\ \frac{\partial}{\partial \mathbf{x}_2} (\mathbf{x}_1 - \mathbf{x}_1 \mathbf{x}_2 + \mathbf{x}_3^2) \\ \frac{\partial}{\partial \mathbf{x}_3} (\mathbf{x}_1 - \mathbf{x}_1 \mathbf{x}_2 + \mathbf{x}_3^2) \end{bmatrix} = \begin{bmatrix} 1 - \mathbf{x}_2 \\ -\mathbf{x}_1 \\ 2\mathbf{x}_3 \end{bmatrix}$$



▶ To minimize $J(\mathbf{w})$, we can simply solve for where its gradient is 0: $\nabla_{\mathbf{w}}J(\mathbf{w}) = 0$

 $\hat{\mathbf{y}} = \mathbf{w}^{\mathsf{T}} \mathbf{x}$



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 $\hat{\mathbf{y}} = \mathbf{w}^{\mathsf{T}} \mathbf{X}^{\mathsf{T}}$ or $\hat{\mathbf{y}} = \mathbf{X} \mathbf{w}$





► To minimize $J(\mathbf{w})$, we can simply solve for where its gradient is 0: $\nabla_{\mathbf{w}} J(\mathbf{w}) = 0$ $J(\mathbf{w}) = \frac{1}{m} ||\hat{\mathbf{y}} - \mathbf{y}||_2^2, \nabla_{\mathbf{w}} J(\mathbf{w}) = 0$



$$\begin{split} \mathbf{J}(\mathbf{w}) &= \frac{1}{m} ||\mathbf{\hat{y}} - \mathbf{y}||_2^2, \nabla_{\mathbf{w}} \mathbf{J}(\mathbf{w}) = \mathbf{0} \\ &\Rightarrow \nabla_{\mathbf{w}} \frac{1}{m} ||\mathbf{\hat{y}} - \mathbf{y}||_2^2 = \mathbf{0} \end{split}$$



$$J(\mathbf{w}) = \frac{1}{m} ||\hat{\mathbf{y}} - \mathbf{y}||_2^2, \nabla_{\mathbf{w}} J(\mathbf{w}) = 0$$

$$\Rightarrow \nabla_{\mathbf{w}} \frac{1}{m} ||\hat{\mathbf{y}} - \mathbf{y}||_2^2 = 0$$

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$$\Rightarrow 2\mathbf{X}^{\mathsf{T}} \mathbf{X} \mathbf{w} - 2\mathbf{X}^{\mathsf{T}} \mathbf{y} = 0$$



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Normal Equation - Example (1/7)

Living area	No. of bedrooms	Price
2104	3	400
1600	3	330
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1416	2	232
3000	4	540

• Predict the value of \hat{y} , when $x_1 = 4000$ and $x_2 = 4$.



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- Predict the value of \hat{y} , when $x_1 = 4000$ and $x_2 = 4$.
- We should find w_0 , w_1 , and w_2 in $\hat{y} = w_0 + w_1 x_1 + w_2 x_2$.
- $\blacktriangleright \mathbf{w} = (\mathbf{X}^{\mathsf{T}}\mathbf{X})^{-1}\mathbf{X}^{\mathsf{T}}\mathbf{y}.$



Normal Equation - Example (2/7)

Livi	ng a	rea	No.	of b	edrooms	Price
2104			3			400
1600			3			330
2400		3			369	
	1416			2		232
;	3000			4		540
	Γ1	210	4 3	1		ך 400 T
	1	160	0 3			330
X =	1	240	0 3		у =	369
	1	141	6 2			232
	L 1	300	0 4]		540



Normal Equation - Example (3/7)





Normal Equation - Example (4/7)

	4.90366455e + 00	7.48766737e - 04	-2.09302326e + 00]
$({\bf X}^{\intercal}{\bf X})^{-1} =$	7.48766737e - 04	2.75281889e - 06	-2.18023256e - 03
	-2.09302326e + 00	-2.18023256e - 03	2.22674419e + 00



Normal Equation - Example (5/7)

$$\mathbf{X}^{\mathsf{T}}\mathbf{y} = \begin{bmatrix} 1 & 1 & 1 & 1 & 1 \\ 2104 & 1600 & 2400 & 1416 & 3000 \\ 3 & 3 & 3 & 2 & 4 \end{bmatrix} \begin{bmatrix} 400 \\ 330 \\ 369 \\ 232 \\ 540 \end{bmatrix} = \begin{bmatrix} 1871 \\ 4203712 \\ 5921 \end{bmatrix}$$



Normal Equation - Example (6/7)

$$\mathbf{w} = (\mathbf{X}^{\mathsf{T}}\mathbf{X})^{-1}\mathbf{X}^{\mathsf{T}}\mathbf{y} = \begin{bmatrix} 4.90366455e + 00 & 7.48766737e - 04 & -2.09302326e + 00 \\ 7.48766737e - 04 & 2.75281889e - 06 & -2.18023256e - 03 \\ -2.09302326e + 00 & -2.18023256e - 03 & 2.22674419e + 00 \end{bmatrix} \begin{bmatrix} 1871 \\ 4203712 \\ 5921 \end{bmatrix}$$
$$= \begin{bmatrix} -7.04346018e + 01 \\ 6.38433756e - 02 \\ 1.03436047e + 02 \end{bmatrix}$$



Normal Equation - Example (7/7)

• Predict the value of y, when $x_1 = 4000$ and $x_2 = 4$.

 $\hat{y} = -7.04346018e + 01 + 6.38433756e - 02 \times 4000 + 1.03436047e + 02 \times 4 \approx 599$



Normal Equation in Spark

val testData = Seq(house(4000, 4, 0)).toDF



Normal Equation in Spark

```
val testData = Seq(house(4000, 4, 0)).toDF
```

import org.apache.spark.ml.feature.VectorAssembler

val va = new VectorAssembler().setInputCols(Array("x1", "x2")).setOutputCol("features")

val train = va.transform(trainData)
val test = va.transform(testData)



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val train = va.transform(trainData)
val test = va.transform(testData)

import org.apache.spark.ml.regression.LinearRegression

```
val lr = new LinearRegression().setFeaturesCol("features").setLabelCol("y").setSolver("normal")
val lrModel = lr.fit(train)
lrModel.transform(test).show
```



Normal Equation - Computational Complexity

- The computational complexity of inverting X^TX is $O(n^3)$.
 - For an $m \times n$ matrix (where n is the number of features).



Normal Equation - Computational Complexity

- The computational complexity of inverting $X^T X$ is $O(n^3)$.
 - For an $m \times n$ matrix (where n is the number of features).
- ▶ But, this equation is linear with regards to the number of instances in the training set (it is O(m)).
 - It handles large training sets efficiently, provided they can fit in memory.





[https://dailyfintech.com/2017/03/13/now-all-we-need-is-for-blockchain-to-become-technologically-boring]



Gradient Descent



Gradient Descent (1/2)

- Gradient descent is a generic optimization algorithm capable of finding optimal solutions to a wide range of problems.
- ▶ The idea: to tweak parameters iteratively in order to minimize a cost function.





Gradient Descent (2/2)

- Suppose you are lost in the mountains in a dense fog.
- ► You can only feel the slope of the ground below your feet.
- A strategy to get to the bottom of the valley is to go downhill in the direction of the steepest slope.




► Choose a starting point, e.g., filling **w** with random values.





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- ▶ If the stopping criterion is true return the current solution, otherwise continue.





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- ► Find a descent direction, a direction in which the function value decreases near the current point.





- ► Choose a starting point, e.g., filling **w** with random values.
- ▶ If the stopping criterion is true return the current solution, otherwise continue.
- Find a descent direction, a direction in which the function value decreases near the current point.
- Determine the step size, the length of a step in the given direction.





Gradient Descent - Key Points

- Stopping criterion
- Descent direction
- Step size (learning rate)



Gradient Descent - Stopping Criterion

▶ The cost function minimum property: the gradient has to be zero.

 $\nabla_{\mathbf{w}} J(\mathbf{w}) = 0$





Gradient Descent - Descent Direction (1/2)

- ▶ Direction in which the function value decreases near the current point.
- Find the direction of descent (slope).



Gradient Descent - Descent Direction (1/2)

- Direction in which the function value decreases near the current point.
- ► Find the direction of descent (slope).
- Example:





Gradient Descent - Descent Direction (2/2)

• Follow the opposite direction of the slope.





Gradient Descent - Learning Rate

• Learning rate: the length of steps.



Gradient Descent - Learning Rate

- Learning rate: the length of steps.
- ▶ If it is too small: many iterations to converge.





Gradient Descent - Learning Rate

- Learning rate: the length of steps.
- ▶ If it is too small: many iterations to converge.

• If it is too high: the algorithm might diverge.





• Goal: find w that minimizes $J(w) = \sum_{i=1}^{m} (w^{\mathsf{T}} x^{(i)} - y^{(i)})^2$.



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- Start at a random point, and repeat the following steps, until the stopping criterion is satisfied:





- Goal: find w that minimizes $J(w) = \sum_{i=1}^{m} (w^{\mathsf{T}} x^{(i)} y^{(i)})^2$.
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 - 1. Determine a descent direction $\frac{\partial J(w)}{\partial w}$





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- Start at a random point, and repeat the following steps, until the stopping criterion is satisfied:
 - 1. Determine a descent direction $\frac{\partial J(w)}{\partial w}$
 - 2. Choose a step size η





- Goal: find w that minimizes $J(w) = \sum_{i=1}^{m} (w^{\mathsf{T}} x^{(i)} y^{(i)})^2$.
- Start at a random point, and repeat the following steps, until the stopping criterion is satisfied:
 - 1. Determine a descent direction $\frac{\partial J(w)}{\partial w}$
 - 2. Choose a step size η
 - 3. Update the parameters: $w^{(next)} = w \eta \frac{\partial J(w)}{\partial w}$ (should be done for all parameters simultanously)





Gradient Descent - Different Algorithms

- Batch gradient descent
- Stochastic gradient descent
- Mini-batch gradient descent



[https://towardsdatascience.com/gradient-descent-algorithm-and-its-variants-10f652806a3]



Batch Gradient Descent



Batch Gradient Descent (1/2)

- ▶ Repeat the following steps, until the stopping criterion is satisfied:
 - 1. Determine a descent direction $\frac{\partial J(w)}{\partial w}$ for all parameters w.

$$J(\boldsymbol{w}) = \sum_{i=1}^{m} (\boldsymbol{w}^{\mathsf{T}} \boldsymbol{x}^{(i)} - \boldsymbol{y}^{(i)})^2$$



Batch Gradient Descent (1/2)

- ▶ Repeat the following steps, until the stopping criterion is satisfied:
 - 1. Determine a descent direction $\frac{\partial J(w)}{\partial w}$ for all parameters w.

$$J(\mathbf{w}) = \sum_{i=1}^{m} (\mathbf{w}^{\mathsf{T}} \mathbf{x}^{(i)} - \mathbf{y}^{(i)})^2$$

$$\frac{\partial J(\mathbf{w})}{\partial w_{j}} = \frac{2}{m} \sum_{i=1}^{m} (\mathbf{w}^{\mathsf{T}} \mathbf{x}^{(i)} - \mathbf{y}^{(i)}) \mathbf{x}_{j}^{(i)} \qquad \nabla_{\mathbf{w}} J(\mathbf{w}) = \begin{bmatrix} \frac{\partial J(\mathbf{w})}{\partial w_{0}} \\ \frac{\partial J(\mathbf{w})}{\partial w_{1}} \\ \vdots \\ \frac{\partial J(\mathbf{w})}{\partial w_{n}} \end{bmatrix} = \frac{2}{m} \mathbf{X}^{\mathsf{T}} (\mathbf{X} \mathbf{w} - \mathbf{y})$$

2. Choose a step size η



Batch Gradient Descent (1/2)

- ▶ Repeat the following steps, until the stopping criterion is satisfied:
 - 1. Determine a descent direction $\frac{\partial J(w)}{\partial w}$ for all parameters w.

$$J(\mathbf{w}) = \sum_{i=1}^{m} (\mathbf{w}^{\mathsf{T}} \mathbf{x}^{(i)} - \mathbf{y}^{(i)})^2$$

$$\frac{\partial J(\mathbf{w})}{\partial w_{j}} = \frac{2}{m} \sum_{i=1}^{m} (\mathbf{w}^{\mathsf{T}} \mathbf{x}^{(i)} - \mathbf{y}^{(i)}) \mathbf{x}_{j}^{(i)} \qquad \nabla_{\mathbf{w}} J(\mathbf{w}) = \begin{bmatrix} \frac{\partial J(\mathbf{w})}{\partial w_{1}} \\ \frac{\partial J(\mathbf{w})}{\partial w_{1}} \\ \vdots \\ \frac{\partial J(\mathbf{w})}{\partial w_{n}} \end{bmatrix} = \frac{2}{m} \mathbf{X}^{\mathsf{T}} (\mathbf{X} \mathbf{w} - \mathbf{y})$$

- 2. Choose a step size η
- 3. Update the parameters: $\mathbf{w}^{(\text{next})} = \mathbf{w} \eta \nabla_{\mathbf{w}} J(\mathbf{w})$



Batch Gradient Descent (2/2)

- ► The algorithm is called Batch Gradient Descent, because at each step, calculations are over the full training set X.
- ▶ As a result it is slow on very large training sets, i.e., large m.
- ▶ But, it scales well with the number of features n.



Batch Gradient Descent - Example (1/5)

No. of bedrooms	Price
3	400
3	330
3	369
2	232
4	540
	No. of bedrooms 3 3 3 2 4

 $\hat{y} = w_0 + w_1 x_1 + w_2 x_2$

	1	2104	3 -		[400]
	1	1600	3		330
X =	1	2400	3	y =	369
	1	1416	2		232
	_ 1	3000	4		540



Batch Gradient Descent - Example (2/5)

$$\mathbf{X} = \begin{bmatrix} 1 & 2104 & 3 \\ 1 & 1600 & 3 \\ 1 & 2400 & 3 \\ 1 & 1416 & 2 \\ 1 & 3000 & 4 \end{bmatrix} \qquad \mathbf{y} = \begin{bmatrix} 400 \\ 330 \\ 369 \\ 232 \\ 540 \end{bmatrix}$$

$$\begin{aligned} \frac{\partial J(\mathbf{w})}{\partial w_0} &= \frac{2}{m} \sum_{i=1}^{m} (\mathbf{w}^T \mathbf{x}^{(i)} - \mathbf{y}^{(i)}) \mathbf{x}_0^{(i)} \\ &= \frac{2}{5} [(w_0 + 2104w_1 + 3w_2 - 400) + (w_0 + 1600w_1 + 3w_2 - 330) + (w_0 + 2400w_1 + 3w_2 - 369) + (w_0 + 1416w_1 + 2w_2 - 232) + (w_0 + 3000w_1 + 4w_2 - 540)] \end{aligned}$$



Batch Gradient Descent - Example (3/5)

$$\mathbf{X} = \begin{bmatrix} 1 & 2104 & 3 \\ 1 & 1600 & 3 \\ 1 & 2400 & 3 \\ 1 & 1416 & 2 \\ 1 & 3000 & 4 \end{bmatrix} \qquad \mathbf{y} = \begin{bmatrix} 400 \\ 330 \\ 369 \\ 232 \\ 540 \end{bmatrix}$$

$$\begin{aligned} \frac{\partial J(\mathbf{w})}{\partial w_1} &= \frac{2}{m} \sum_{i=1}^m (\mathbf{w}^\mathsf{T} \mathbf{x}^{(i)} - \mathbf{y}^{(i)}) \mathbf{x}_1^{(i)} \\ &= \frac{2}{5} [2104(w_0 + 2104w_1 + 3w_2 - 400) + 1600(w_0 + 1600w_1 + 3w_2 - 330) + \\ &\quad 2400(w_0 + 2400w_1 + 3w_2 - 369) + 1416(w_0 + 1416w_1 + 2w_2 - 232) + 3000(w_0 + 3000w_1 + 4w_2 - 540)] \end{aligned}$$



Batch Gradient Descent - Example (4/5)

$$\mathbf{X} = \begin{bmatrix} 1 & 2104 & 3 \\ 1 & 1600 & 3 \\ 1 & 2400 & 3 \\ 1 & 1416 & 2 \\ 1 & 3000 & 4 \end{bmatrix} \qquad \mathbf{y} = \begin{bmatrix} 400 \\ 330 \\ 369 \\ 232 \\ 540 \end{bmatrix}$$

$$\begin{aligned} \frac{\partial J(\mathbf{w})}{\partial \mathbf{w}_2} &= \frac{2}{m} \sum_{i=1}^{m} (\mathbf{w}^{\mathsf{T}} \mathbf{x}^{(i)} - \mathbf{y}^{(i)}) \mathbf{x}_2^{(i)} \\ &= \frac{2}{5} [3(\mathbf{w}_0 + 2104\mathbf{w}_1 + 3\mathbf{w}_2 - 400) + 3(\mathbf{w}_0 + 1600\mathbf{w}_1 + 3\mathbf{w}_2 - 330) + \\ &\quad 3(\mathbf{w}_0 + 2400\mathbf{w}_1 + 3\mathbf{w}_2 - 369) + 2(\mathbf{w}_0 + 1416\mathbf{w}_1 + 2\mathbf{w}_2 - 232) + 4(\mathbf{w}_0 + 3000\mathbf{w}_1 + 4\mathbf{w}_2 - 540)] \end{aligned}$$



Batch Gradient Descent - Example (5/5)

$$\begin{split} \mathbf{w}_{0}^{(\text{next})} &= \mathbf{w}_{0} - \eta \frac{\partial J(\mathbf{w})}{\partial \mathbf{w}_{0}} \\ \mathbf{w}_{1}^{(\text{next})} &= \mathbf{w}_{1} - \eta \frac{\partial J(\mathbf{w})}{\partial \mathbf{w}_{1}} \\ \mathbf{w}_{2}^{(\text{next})} &= \mathbf{w}_{2} - \eta \frac{\partial J(\mathbf{w})}{\partial \mathbf{w}_{2}} \end{split}$$



Stochastic Gradient Descent





Stochastic Gradient Descent (1/3)

Batch gradient descent problem: it's slow, because it uses the whole training set to compute the gradients at every step.



Stochastic Gradient Descent (1/3)

- Batch gradient descent problem: it's slow, because it uses the whole training set to compute the gradients at every step.
- ► Stochastic gradient descent computes the gradients based on only a single instance.
 - It picks a random instance in the training set at every step.



Stochastic Gradient Descent (2/3)

▶ The algorithm is much faster, but less regular than batch gradient descent.





Stochastic Gradient Descent (2/3)

- ▶ The algorithm is much faster, but less regular than batch gradient descent.
 - Instead of decreasing until it reaches the minimum, the cost function will bounce up and down.
 - It never settles down.





Stochastic Gradient Descent (3/3)

- With randomness the algorithm can never settle at the minimum.
- One solution is simulated annealing: start with large learning rate, then make it smaller and smaller.



Stochastic Gradient Descent (3/3)

- With randomness the algorithm can never settle at the minimum.
- One solution is simulated annealing: start with large learning rate, then make it smaller and smaller.
- Learning schedule: the function that determines the learning rate at each step.



Stochastic Gradient Descent - Example (1/3)

Living area	No. of bedrooms	Price
2104	3	400
1600	3	330
2400	3	369
1416	2	232
3000	4	540

 $\hat{\mathbf{y}} = \mathbf{w}_0 + \mathbf{w}_1 \mathbf{x}_1 + \mathbf{w}_2 \mathbf{x}_2$

	1	2104	3 -		[400]
	1	1600	3		330
X =	1	2400	3	y =	369
	1	1416	2		232
	1	3000	4		540


Stochastic Gradient Descent - Example (2/3)

$$\mathbf{X} = \begin{bmatrix} 1 & 2104 & 3 \\ 1 & 1600 & 3 \\ 1 & 2400 & 3 \\ 1 & 1416 & 2 \\ 1 & 3000 & 4 \end{bmatrix} \qquad \mathbf{y} = \begin{bmatrix} 400 \\ 330 \\ 369 \\ 232 \\ 540 \end{bmatrix}$$

$$\begin{aligned} \frac{\partial J(\mathbf{w})}{\partial w_0} &= \frac{2}{m} (\mathbf{w}^\mathsf{T} \mathbf{x}^{(i)} - y^{(i)}) \mathbf{x}_0^{(i)} = \frac{2}{5} [(w_0 + 1600w_1 + 3w_2 - 330)] \\ \frac{\partial J(\mathbf{w})}{\partial w_1} &= \frac{2}{m} (\mathbf{w}^\mathsf{T} \mathbf{x}^{(i)} - y^{(i)}) \mathbf{x}_1^{(i)} = \frac{2}{5} [1600(w_0 + 1600w_1 + 3w_2 - 330)] \\ \frac{\partial J(\mathbf{w})}{\partial w_2} &= \frac{2}{m} (\mathbf{w}^\mathsf{T} \mathbf{x}^{(i)} - y^{(i)}) \mathbf{x}_2^{(i)} = \frac{2}{5} [3(w_0 + 1600w_1 + 3w_2 - 330)] \end{aligned}$$



Stochastic Gradient Descent - Example (3/3)

$$\begin{split} \mathbf{w}_{0}^{(\text{next})} &= \mathbf{w}_{0} - \eta \frac{\partial \mathbf{J}(\mathbf{w})}{\partial \mathbf{w}_{0}} \\ \mathbf{w}_{1}^{(\text{next})} &= \mathbf{w}_{1} - \eta \frac{\partial \mathbf{J}(\mathbf{w})}{\partial \mathbf{w}_{1}} \\ \mathbf{w}_{2}^{(\text{next})} &= \mathbf{w}_{2} - \eta \frac{\partial \mathbf{J}(\mathbf{w})}{\partial \mathbf{w}_{2}} \end{split}$$



Mini-Batch Gradient Descent



Mini-Batch Gradient Descent

- Batch gradient descent: at each step, it computes the gradients based on the full training set.
- Stochastic gradient descent: at each step, it computes the gradients based on just one instance.
- Mini-batch gradient descent: at each step, it computes the gradients based on small random sets of instances called mini-batches.



Comparison of Algorithms for Linear Regression

Algorithm	Large <i>m</i>	Large <i>n</i>
Normal Equation	Fast	Slow
Batch GD	Slow	Fast
Stochastic GD	Fast	Fast
Mini-batch GD	Fast	Fast





Gradient Descent in Spark

val data = spark.read.format("libsvm").load("data.txt")



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```
import org.apache.spark.ml.regression.LinearRegression
val lr = new LinearRegression().setMaxIter(10)
val lrModel = lr.fit(data)
```



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import org.apache.spark.ml.regression.LinearRegression
```

```
val lr = new LinearRegression().setMaxIter(10)
```

```
val lrModel = lr.fit(data)
```

println(s"Coefficients: \${lrModel.coefficients} Intercept: \${lrModel.intercept}")

```
val trainingSummary = lrModel.summary
println(s"RMSE: ${trainingSummary.rootMeanSquaredError}")
```



Generalization



Training Data and Test Data

• Split data into a training set and a test set.





Training Data and Test Data

- Split data into a training set and a test set.
- ► Use training set when training a machine learning model.
 - Compute training error on the training set.
 - Try to reduce this training error.

	Full Dataset:		
<pre>val data = spark.read.format("libsvm").load("data.txt")</pre>	Training Data	Test Data	
<pre>val Array(trainDF, testDF) = data.randomSplit(Array(0.8, 0.2))</pre>			

Full Determine



Training Data and Test Data

- Split data into a training set and a test set.
- ► Use training set when training a machine learning model.
 - Compute training error on the training set.
 - Try to reduce this training error.
- ► Use test set to measure the accuracy of the model.
 - Test error is the error when you run the trained model on test data (new data).

Full Dataset:

<pre>val data = spark.read.format("libsvm").load("data.txt")</pre>	<pre>data = spark.read.format("libsvm").load("data.txt")</pre>		
<pre>val Array(trainDF, testDF) = data.randomSplit(Array(0.8, 0.2))</pre>	Training Data	Test Data	



- Generalization: make a model that performs well on test data.
 - Have a small test error.



- Generalization: make a model that performs well on test data.
 - Have a small test error.
- Challenges
 - 1. Make the training error small.
 - 2. Make the gap between training and test error small.



More About The Test Error

► The test error is defined as the expected value of the error on test set.

$$MSE = rac{1}{k} \sum_i^k (\hat{y}^{(i)} - y^{(i)})^2$$
, k: the num. of instances in the test set $= E[(\hat{y} - y)^2]$



More About The Test Error

► The test error is defined as the expected value of the error on test set.

$$\begin{split} \text{MSE} &= \frac{1}{k}\sum_{i}^{k}(\hat{y}^{(i)}-y^{(i)})^2, \text{ k: the num. of instances in the test set} \\ &= \text{E}[(\hat{y}-y)^2] \end{split}$$

• A model's test error can be expressed as the sum of bias and variance.

$$\mathbf{E}[(\mathbf{\hat{y}} - \mathbf{y})^2] = \mathbf{Bias}[\mathbf{\hat{y}}, \mathbf{y}]^2 + \mathbf{Var}[\mathbf{\hat{y}}] + \varepsilon^2$$







▶ Bias: the expected deviation from the true value of the function.

 $\texttt{Bias}[\boldsymbol{\hat{y}}, \boldsymbol{y}] = \texttt{E}[\boldsymbol{\hat{y}}] - \boldsymbol{y}$



Bias and Underfitting

• Bias: the expected deviation from the true value of the function.

 $\texttt{Bias}[\hat{\mathtt{y}},\mathtt{y}] = \mathtt{E}[\hat{\mathtt{y}}] - \mathtt{y}$

- A high-bias model is most likely to underfit the training data.
 - High error value on the training set.





Bias and Underfitting

▶ Bias: the expected deviation from the true value of the function.

 $\texttt{Bias}[\boldsymbol{\hat{y}}, \boldsymbol{y}] = \texttt{E}[\boldsymbol{\hat{y}}] - \boldsymbol{y}$

- A high-bias model is most likely to underfit the training data.
 - High error value on the training set.
- Underfitting happens when the model is too simple to learn the underlying structure of the data.





Variance and Overfitting

► Variance: how much a model changes if you train it on a different training set.
Var[ŷ] = E[(ŷ - E[ŷ])²]



Variance and Overfitting

- ► Variance: how much a model changes if you train it on a different training set. Var[ŷ] = E[(ŷ - E[ŷ])²]
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Variance and Overfitting

- ► Variance: how much a model changes if you train it on a different training set. Var[ŷ] = E[(ŷ - E[ŷ])²]
- A high-variance model is most likely to overfit the training data.
 - The gap between the training error and test error is too large.
- Overfitting happens when the model is too complex relative to the amount and noisiness of the training data.





• Assume a model with two parameters w_0 (intercept) and w_1 (slope): $\hat{y} = w_0 + w_1 x$



- ▶ Assume a model with two parameters w_0 (intercept) and w_1 (slope): $\hat{y} = w_0 + w_1 x$
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- ▶ Assume a model with two parameters w_0 (intercept) and w_1 (slope): $\hat{y} = w_0 + w_1 x$
- ► They give the learning algorithm two degrees of freedom.
- We tweak both the w_0 and w_1 to adapt the model to the training data.
- ► If we forced w₀ = 0, the algorithm would have only one degree of freedom and would have a much harder time fitting the data properly.



- ► Increasing degrees of freedom will typically increase its variance and reduce its bias.
- ► Decreasing degrees of freedom increases its bias and reduces its variance.
- This is why it is called a tradeoff.



[https://ml.berkeley.edu/blog/2017/07/13/tutorial-4]



Regularization (1/2)

- One way to reduce the risk of overfitting is to have fewer degrees of freedom.
- Regularization is a technique to reduce the risk of overfitting.
- For a linear model, regularization is achieved by constraining the weights of the model.

 $J(\mathbf{w}) = MSE(\mathbf{w}) + \lambda R(\mathbf{w})$



Regularization (2/2)

▶ Lasso regression (/1): $\mathbb{R}(\mathbf{w}) = \lambda \sum_{i=1}^{n} |\mathbf{w}_i|$ is added to the cost function:

$$\mathbf{J}(\mathbf{w}) = \mathtt{MSE}(\mathbf{w}) + \lambda \sum_{\mathtt{i}=1}^{n} |\mathbf{w}_{\mathtt{i}}|$$



Regularization (2/2)

- ► Lasso regression (/1): $\mathbb{R}(\mathbf{w}) = \lambda \sum_{i=1}^{n} |\mathbf{w}_i|$ is added to the cost function: $J(\mathbf{w}) = \mathbb{MSE}(\mathbf{w}) + \lambda \sum_{i=1}^{n} |\mathbf{w}_i|$
- Ridge regression (/2): $\mathbb{R}(\mathbf{w}) = \lambda \sum_{i=1}^{n} w_i^2$ is added to the cost function. $J(\mathbf{w}) = MSE(\mathbf{w}) + \lambda \sum_{i=1}^{n} w_i^2$



Regularization (2/2)

- ► Lasso regression (/1): $\mathbb{R}(\mathbf{w}) = \lambda \sum_{i=1}^{n} |\mathbf{w}_i|$ is added to the cost function: $J(\mathbf{w}) = \mathbb{MSE}(\mathbf{w}) + \lambda \sum_{i=1}^{n} |\mathbf{w}_i|$
- ► Ridge regression (/2): $R(\mathbf{w}) = \lambda \sum_{i=1}^{n} w_i^2$ is added to the cost function. $J(\mathbf{w}) = MSE(\mathbf{w}) + \lambda \sum_{i=1}^{n} w_i^2$
- ► ElasticNet: a middle ground between /1 and /2 regularization. $J(\mathbf{w}) = MSE(\mathbf{w}) + \alpha\lambda \sum_{i=1}^{n} |w_i| + (1 - \alpha)\lambda \sum_{i=1}^{n} w_i^2$



Regularization in Spark

$$J(\mathbf{w}) = \texttt{MSE}(\mathbf{w}) + \alpha \lambda \sum_{i=1}^{n} |\mathbf{w}_i| + (1 - \alpha) \lambda \sum_{i=1}^{n} \mathbf{w}_i^2$$

- If $\alpha = 0$: /2 regularization
- If $\alpha = 1$: /1 regularization
- For α in (0, 1): a combination of /1 and /2 regularizations

```
import org.apache.spark.ml.regression.LinearRegression
val lr = new LinearRegression().setElasticNetParam(0.8)
val lrModel = lr.fit(data)
```



Hyperparameters



Hyperparameters and Validation Sets (1/2)

Hyperparameters are settings that we can use to control the behavior of a learning algorithm.



Hyperparameters and Validation Sets (1/2)

- ► Hyperparameters are settings that we can use to control the behavior of a learning algorithm.
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 - E.g., the α and λ values for regularization.


Hyperparameters and Validation Sets (1/2)

- ► Hyperparameters are settings that we can use to control the behavior of a learning algorithm.
- ► The values of hyperparameters are not adapted by the learning algorithm itself.
 - E.g., the α and λ values for regularization.
- We do not learn the hyperparameter.
 - It is not appropriate to learn that hyperparameter on the training set.
 - If learned on the training set, such hyperparameters would always result in overfitting.



Hyperparameters and Validation Sets (2/2)

► To find hyperparameters, we need a validation set of examples that the training algorithm does not observe.



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Hyperparameters and Validation Sets (2/2)

- ► To find hyperparameters, we need a validation set of examples that the training algorithm does not observe.
- ▶ We construct the validation set from the training data (not the test data).
- ▶ We split the training data into two disjoint subsets:
 - 1. One is used to learn the parameters.
 - 2. The other one (the validation set) is used to estimate the test error during or after training, allowing for the hyperparameters to be updated accordingly.

Full Dataset:		
Training Data	Validation Data	Test Data



 Cross-validation: a technique to avoid wasting too much training data in validation sets.





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- ▶ The training set is split into complementary subsets.





Cross-Validation

- Cross-validation: a technique to avoid wasting too much training data in validation sets.
- ► The training set is split into complementary subsets.
- Each model is trained against a different combination of these subsets and validated against the remaining parts.





Cross-Validation

- Cross-validation: a technique to avoid wasting too much training data in validation sets.
- The training set is split into complementary subsets.
- Each model is trained against a different combination of these subsets and validated against the remaining parts.
- Once the model type and hyperparameters have been selected, a final model is trained using these hyperparameters on the full training set, and the test error is measured on the test set.





Hyperparameters and Cross-Validation in Spark (1/2)

- CrossValidator to optimize hyperparameters in algorithms and model selection.
- It requires the following items:
 - Estimator: algorithm or Pipeline to tune.
 - Set of ParamMaps: parameters to choose from (also called a parameter grid).
 - Evaluator: metric to measure how well a fitted Model does on held-out test data.



Hyperparameters and Cross-Validation in Spark (2/2)

```
// construct a grid of parameters to search over.
// this grid has 2 x 2 = 4 parameter settings for CrossValidator to choose from.
val paramGrid = new ParamGridBuilder()
.addGrid(lr.regParam, Array(0.1, 0.01))
.addGrid(lr.elasticNetParam, Array(0.0, 1.0))
.build()
```



Hyperparameters and Cross-Validation in Spark (2/2)

```
// construct a grid of parameters to search over.
// this grid has 2 x 2 = 4 parameter settings for CrossValidator to choose from.
val paramGrid = new ParamGridBuilder()
.addGrid(lr.regParam, Array(0.1, 0.01))
.addGrid(lr.elasticNetParam, Array(0.0, 1.0))
.build()
```

```
val lr = new LinearRegression()
// num folds = 3 => (2 x 2) x 3 = 12 different models being trained
val cv = new CrossValidator()
.setEstimator(lr)
.setEvaluator(new RegressionEvaluator())
.setEstimatorParamMaps(paramGrid)
.setNumFolds(3)
```

```
val cvModel = cv.fit(trainDF)
```



Summary





- Linear regression model $\hat{y} = \mathbf{w}^{\mathsf{T}} \mathbf{x}$
 - Learning parameters **w**
 - Cost function J(w)
 - Learn parameters: normal equation, gradient descent (batch, stochastic, mini-batch)
- Generalization
 - Overfitting vs. underfitting
 - Bias vs. variance
 - Regularization: Lasso regression, Ridge regression, ElasticNet
- Hyperparameters and cross-validation



- ▶ Ian Goodfellow et al., Deep Learning (Ch. 4, 5)
- ► Aurélien Géron, Hands-On Machine Learning (Ch. 2, 4)
- ▶ Matei Zaharia et al., Spark The Definitive Guide (Ch. 27)



Questions?