



# Distributed Learning - Data Parallelization

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2020-12-08



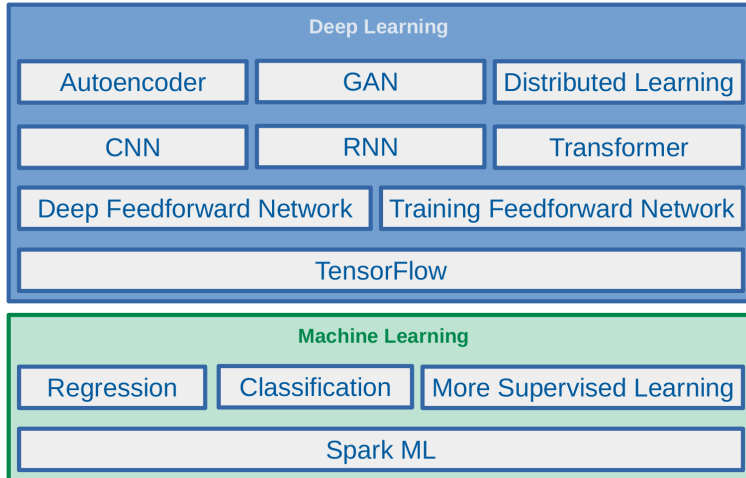


## The Course Web Page

<https://id2223kth.github.io>  
<https://tinyurl.com/y6kcpmzy>

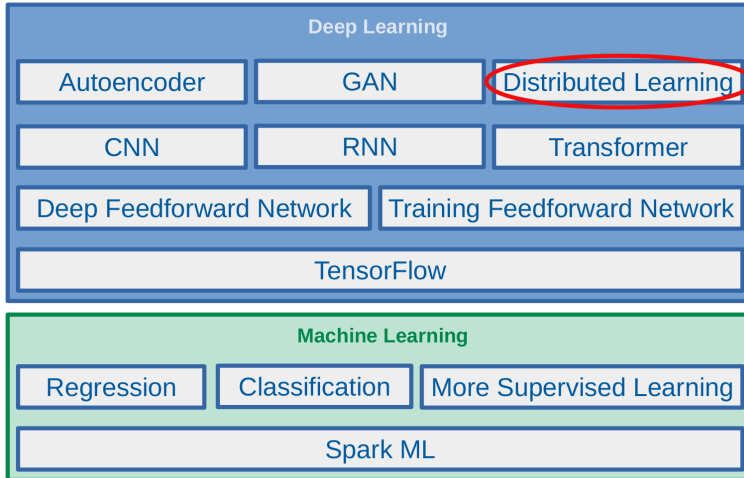


# Where Are We?



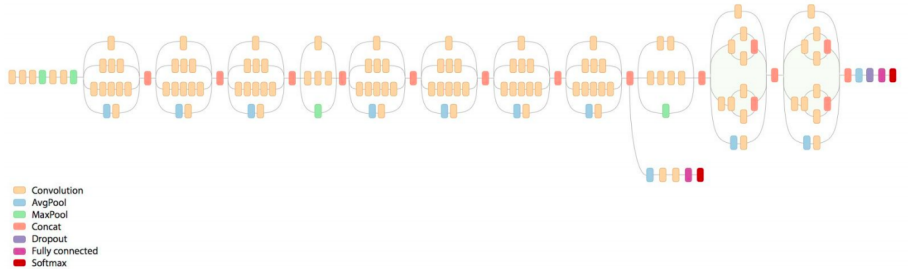


# Where Are We?



# Training Deep Neural Networks

- ▶ Computationally intensive
- ▶ Time consuming



[<https://cloud.google.com/tpu/docs/images/inceptionv3onc--oview.png>]

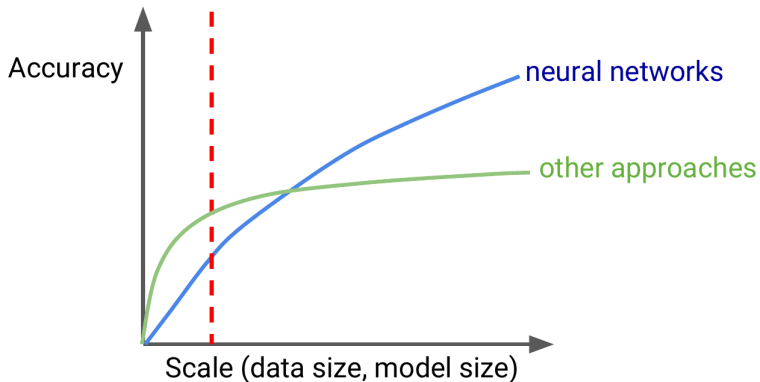
## Why?

- ▶ Massive amount of training dataset
- ▶ Large number of parameters



# Accuracy vs. Data/Model Size

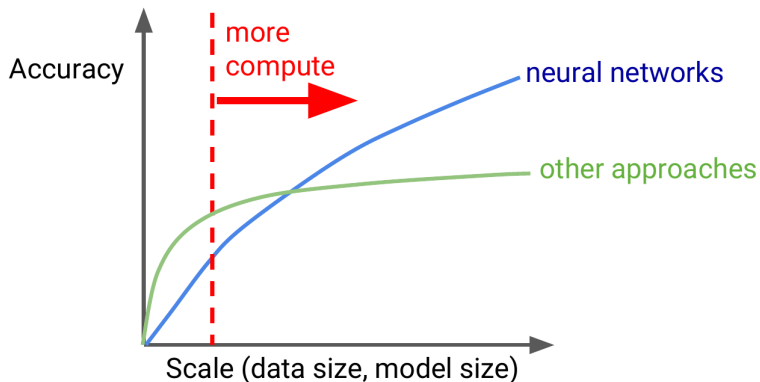
**1980s and 1990s**



[Jeff Dean at AI Frontiers: Trends and Developments in Deep Learning Research]

# Accuracy vs. Data/Model Size

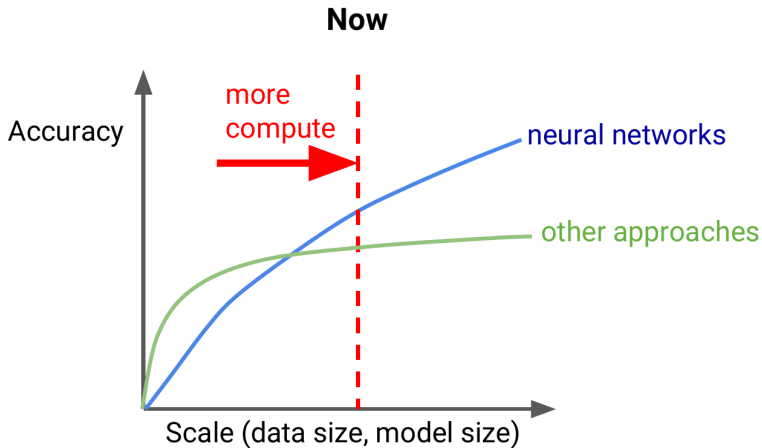
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# Accuracy vs. Data/Model Size



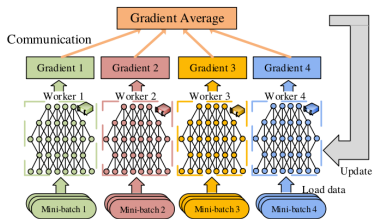
[Jeff Dean at AI Frontiers: Trends and Developments in Deep Learning Research]

Scalability



# Data Parallelization (1/4)

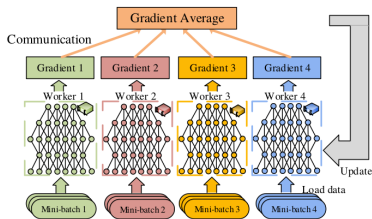
- ▶ Replicate a whole model on every device.



[Tang et al., Communication-Efficient Distributed Deep Learning: A Comprehensive Survey, 2020]

# Data Parallelization (1/4)

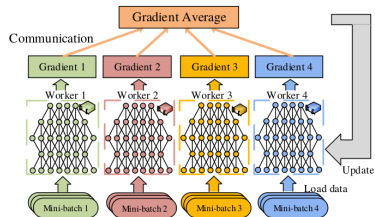
- ▶ Replicate a whole model on every device.
- ▶ Train all replicas simultaneously, using a different mini-batch for each.



[Tang et al., Communication-Efficient Distributed Deep Learning: A Comprehensive Survey, 2020]

# Data Parallelization (2/4)

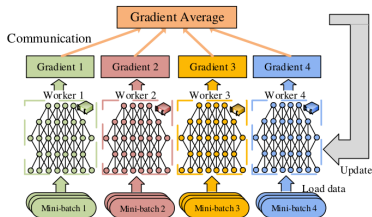
- ▶  $k$  devices



[Tang et al., Communication-Efficient Distributed Deep Learning: A Comprehensive Survey, 2020]

## Data Parallelization (2/4)

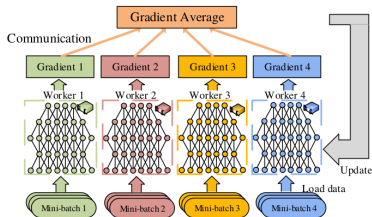
- ▶  $k$  devices
- ▶  $J_i(\mathbf{w}) = \frac{1}{|\beta_i|} \sum_{\mathbf{x} \in \beta_i} l(\mathbf{x}, \mathbf{w}), \forall i = 1, 2, \dots, k$



[Tang et al., Communication-Efficient Distributed Deep Learning: A Comprehensive Survey, 2020]

## Data Parallelization (2/4)

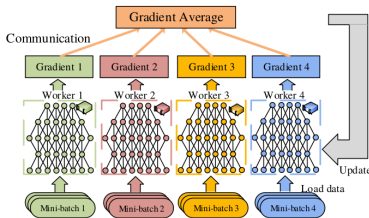
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- ▶  $G_i(\mathbf{w}, \beta_i) = \frac{1}{|\beta_i|} \sum_{\mathbf{x} \in \beta_i} \nabla l(\mathbf{w}, \mathbf{x})$



[Tang et al., Communication-Efficient Distributed Deep Learning: A Comprehensive Survey, 2020]

# Data Parallelization (2/4)

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- ▶  $G_i(\mathbf{w}, \beta_i) = \frac{1}{|\beta_i|} \sum_{\mathbf{x} \in \beta_i} \nabla l(\mathbf{w}, \mathbf{x})$
- ▶  $G_i(\mathbf{w}, \beta_i)$ : the **local estimate** of the gradient of the loss function  $\nabla J_i(\mathbf{w})$ .

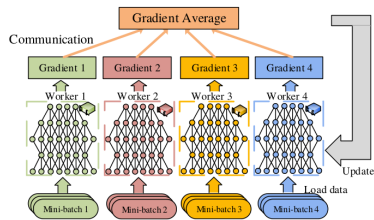


[Tang et al., Communication-Efficient Distributed Deep Learning: A Comprehensive Survey, 2020]



## Data Parallelization (3/4)

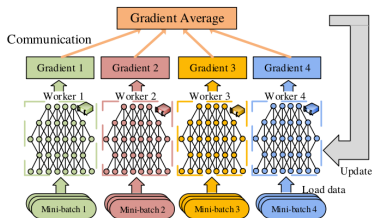
- ▶ Compute the gradients **aggregation** (e.g., **mean of the gradients**).
- ▶  $F(G_1, \dots, G_k) = \frac{1}{k} \sum_{i=1}^k G_i(\mathbf{w}, \beta_i)$



[Tang et al., Communication-Efficient Distributed Deep Learning: A Comprehensive Survey, 2020]

# Data Parallelization (4/4)

- ▶ Update the model.
- ▶  $\mathbf{w} := \mathbf{w} - \eta F(G_1, \dots, G_k)$



[Tang et al., Communication-Efficient Distributed Deep Learning: A Comprehensive Survey, 2020]



# Data Parallelization Design Issues

- ▶ The **aggregation** algorithm
- ▶ Communication **synchronization** and frequency
- ▶ Communication **compression**
- ▶ **Parallelism** of computations and communications



# The Aggregation Algorithm



# The Aggregation Algorithm

- ▶ How to aggregate gradients (compute the mean of the gradients)?



# The Aggregation Algorithm

- ▶ How to **aggregate gradients** (compute the **mean** of the gradients)?
- ▶ Centralized - **parameter server**



# The Aggregation Algorithm

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- ▶ Centralized - **parameter server**
- ▶ Decentralized - **all-reduce**



# The Aggregation Algorithm

- ▶ How to **aggregate gradients** (compute the **mean** of the gradients)?
- ▶ Centralized - **parameter server**
- ▶ Decentralized - **all-reduce**
- ▶ Decentralized - **gossip**



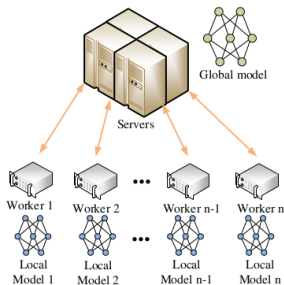


## Aggregation - Centralized - Parameter Server

- ▶ Store the model **parameters** **outside of the workers**.

# Aggregation - Centralized - Parameter Server

- ▶ Store the model **parameters outside of the workers**.
- ▶ **Workers** periodically report their **computed parameters** or **parameter updates** to a (set of) **parameter server(s) (PSs)**.



[Tang et al., Communication-Efficient Distributed Deep Learning: A Comprehensive Survey, 2020]

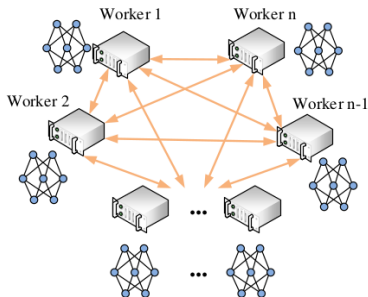


## Aggregation - Distributed - All-Reduce

- ▶ **Mirror** all the model **parameters** **across all workers** (no PS).

## Aggregation - Distributed - All-Reduce

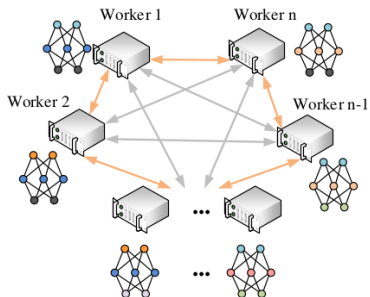
- ▶ **Mirror** all the model **parameters across all workers** (no PS).
- ▶ **Workers exchange** parameter updates **directly** via an **allreduce** operation.



[Tang et al., Communication-Efficient Distributed Deep Learning: A Comprehensive Survey, 2020]

# Aggregation - Distributed - Gossip

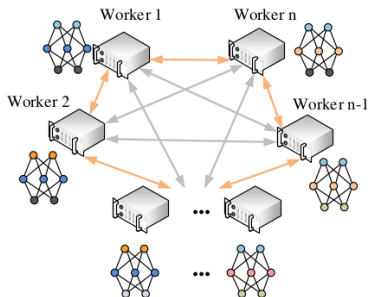
- ▶ No PS, and no global model.



[Tang et al., Communication-Efficient Distributed Deep Learning: A Comprehensive Survey, 2020]

# Aggregation - Distributed - Gossip

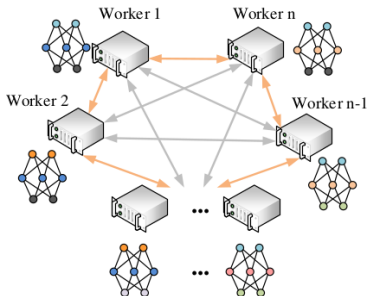
- ▶ No PS, and no global model.
- ▶ Every worker communicates updates with their neighbors.



[Tang et al., Communication-Efficient Distributed Deep Learning: A Comprehensive Survey, 2020]

# Aggregation - Distributed - Gossip

- ▶ No PS, and no global model.
- ▶ Every worker communicates updates with their neighbors.
- ▶ The consistency of parameters across all workers only at the end of the algorithm.



[Tang et al., Communication-Efficient Distributed Deep Learning: A Comprehensive Survey, 2020]



## Reduce and AllReduce (1/2)

- ▶ **Reduce**: reducing a **set of numbers** into a **smaller set of numbers** via a function.



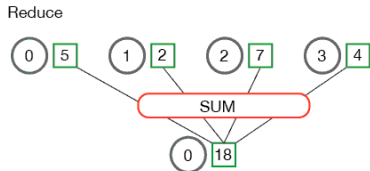


## Reduce and AllReduce (1/2)

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- ▶ E.g.,  $\text{sum}([1, 2, 3, 4, 5]) = 15$

## Reduce and AllReduce (1/2)

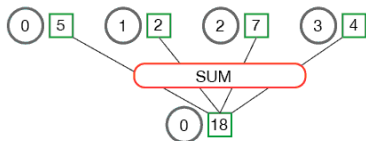
- ▶ **Reduce**: reducing a **set of numbers** into a **smaller set of numbers** via a function.
- ▶ E.g., `sum([1, 2, 3, 4, 5]) = 15`
- ▶ Reduce takes an **array of input** elements on each process and returns an **array of output** elements to the **root process**.



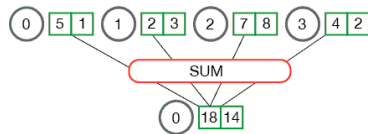
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Reduce



Reduce



[<https://mpitutorial.com/tutorials/mpi-reduce-and-allreduce>]



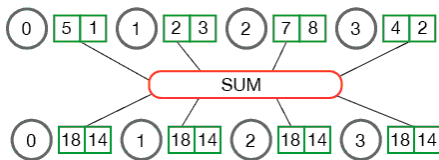
## Reduce and AllReduce (2/2)

- ▶ **AllReduce** stores **reduced results** across **all processes** rather than the root process.

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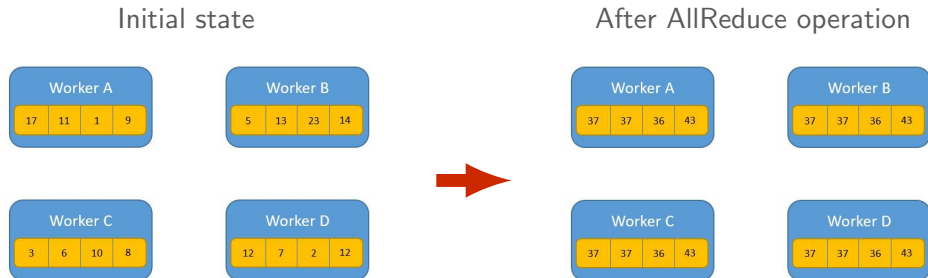
- **AllReduce** stores **reduced results** across **all processes** rather than the root process.

Allreduce



[<https://mpitutorial.com/tutorials/mpi-reduce-and-allreduce>]

# AllReduce Example



[<https://towardsdatascience.com/visual-intuition-on-ring-allreduce-for-distributed-deep-learning-d1f34b4911da>]

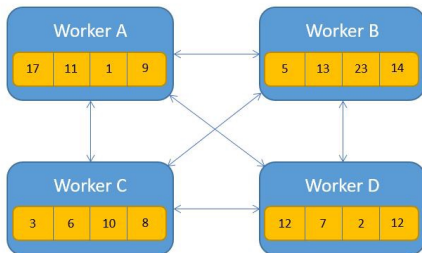


# AllReduce Implementation

- ▶ All-to-all allreduce
- ▶ Master-worker allreduce
- ▶ Tree allreduce
- ▶ Round-robin allreduce
- ▶ Butterfly allreduce
- ▶ Ring allreduce

## AllReduce Implementation - All-to-All AllReduce

- ▶ Send the array of data to each other.
- ▶ Apply the reduction operation on each process.

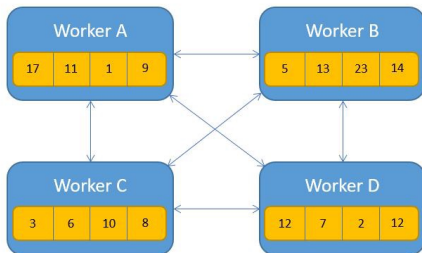


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## AllReduce Implementation - All-to-All AllReduce

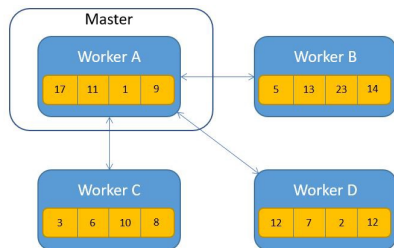
- ▶ Send the array of data to each other.
- ▶ Apply the reduction operation on each process.
- ▶ Too many unnecessary messages.



[<https://towardsdatascience.com/visual-intuition-on-ring-allreduce-for-distributed-deep-learning-d1f34b4911da>]

## AllReduce Implementation - Master-Worker AllReduce

- ▶ Selecting **one process** as a **master**, gather all arrays into the master.
- ▶ Perform **reduction operations** locally in the **master**.
- ▶ **Distribute the result** to the **other processes**.

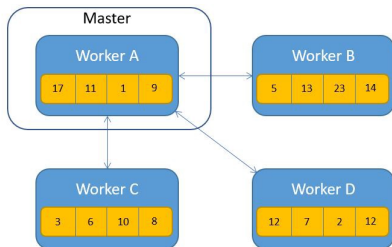


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# AllReduce Implementation - Master-Worker AllReduce

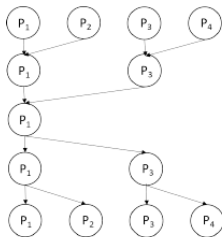
- ▶ Selecting **one process** as a **master**, gather all arrays into the master.
- ▶ Perform **reduction operations** locally in the **master**.
- ▶ **Distribute the result** to the **other processes**.
- ▶ The master becomes a **bottleneck** (**not scalable**).



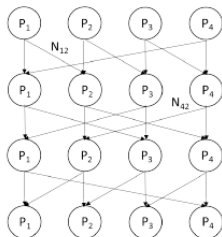
[<https://towardsdatascience.com/visual-intuition-on-ring-allreduce-for-distributed-deep-learning-d1f34b4911da>]

# AllReduce Implementation - Other implementations

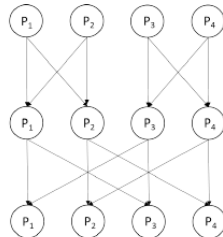
- ▶ Some try to **minimize bandwidth**.
- ▶ Some try to **minimize latency**.



(a) Tree AllReduce



(b) Round-robin AllReduce



(c) Butterfly AllReduce

[Zhao H. et al., arXiv:1312.3020, 2013]

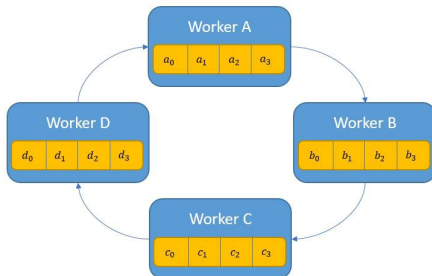


## AllReduce Implementation - Ring-AllReduce (1/6)

- ▶ The **Ring-Allreduce** has **two phases**:
  1. First, the **share-reduce** phase
  2. Then, the **share-only** phase

## AllReduce Implementation - Ring-AllReduce (2/6)

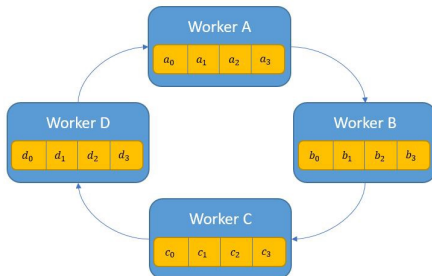
- ▶ In the **share-reduce** phase, each process  $p$  sends data to the process  $(p+1)\%m$ 
  - $m$  is the number of processes, and  $\%$  is the modulo operator.



[<https://towardsdatascience.com/visual-intuition-on-ring-allreduce-for-distributed-deep-learning-d1f34b4911da>]

## AllReduce Implementation - Ring-AllReduce (2/6)

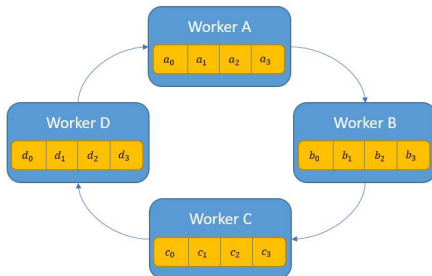
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- ▶ The **array of data** on each process is divided to  $m$  chunks ( $m=4$  here).



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  - $m$  is the number of processes, and  $\%$  is the modulo operator.
- ▶ The **array of data** on each process is divided to  $m$  chunks ( $m=4$  here).
- ▶ Each one of these **chunks** will be **indexed** by  $i$  going forward.

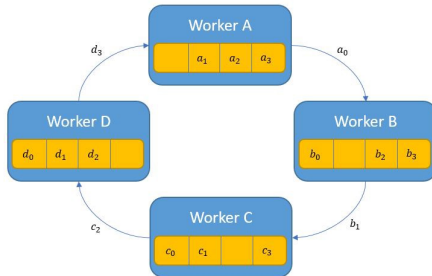


[<https://towardsdatascience.com/visual-intuition-on-ring-allreduce-for-distributed-deep-learning-d1f34b4911da>]



## AllReduce Implementation - Ring-AllReduce (3/6)

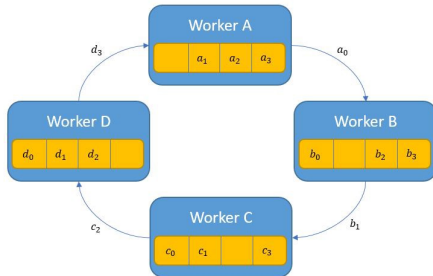
- ▶ In the **first share-reduce step**, process A sends  $a_0$  to process B.



[<https://towardsdatascience.com/visual-intuition-on-ring-allreduce-for-distributed-deep-learning-d1f34b4911da>]

## AllReduce Implementation - Ring-AllReduce (3/6)

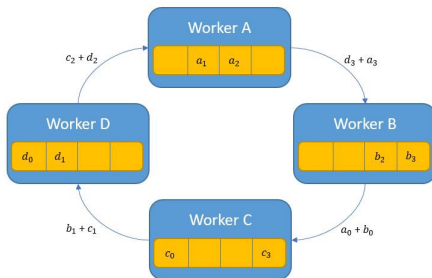
- ▶ In the **first share-reduce step**, process **A** sends  $a_0$  to process **B**.
- ▶ Process **B** sends  $b_1$  to process **C**, etc.



[<https://towardsdatascience.com/visual-intuition-on-ring-allreduce-for-distributed-deep-learning-d1f34b4911da>]

## AllReduce Implementation - Ring-AllReduce (4/6)

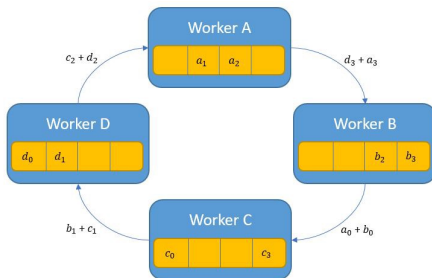
- ▶ When each process receives the data from the previous process, it applies the reduce operator (e.g., sum)



[<https://towardsdatascience.com/visual-intuition-on-ring-allreduce-for-distributed-deep-learning-d1f34b4911da>]

## AllReduce Implementation - Ring-AllReduce (4/6)

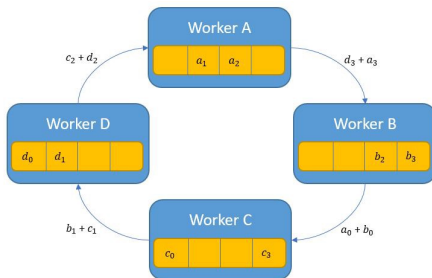
- ▶ When each process receives the data from the previous process, it applies the reduce operator (e.g., sum)
  - The reduce operator should be associative and commutative.



[<https://towardsdatascience.com/visual-intuition-on-ring-allreduce-for-distributed-deep-learning-d1f34b4911da>]

## AllReduce Implementation - Ring-AllReduce (4/6)

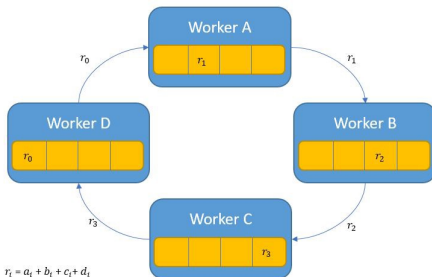
- ▶ When each process receives the data from the previous process, it applies the reduce operator (e.g., sum)
  - The reduce operator should be associative and commutative.
- ▶ It then proceeds to send it to the next process in the ring.



[<https://towardsdatascience.com/visual-intuition-on-ring-allreduce-for-distributed-deep-learning-d1f34b4911da>]

# AllReduce Implementation - Ring-AllReduce (5/6)

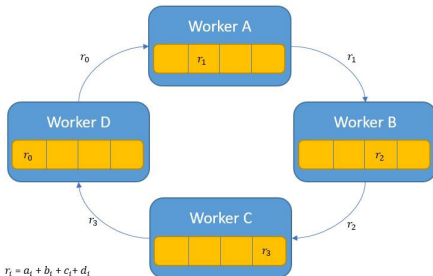
- ▶ The **share-reduce** phase **finishes** when each process holds the **complete reduction** of **chunk i**.



[<https://towardsdatascience.com/visual-intuition-on-ring-allreduce-for-distributed-deep-learning-d1f34b4911da>]

# AllReduce Implementation - Ring-AllReduce (5/6)

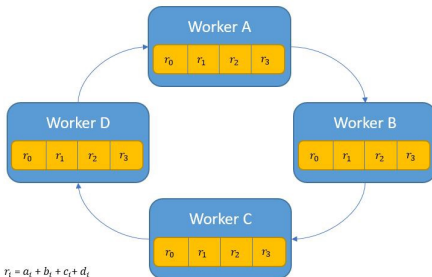
- ▶ The **share-reduce** phase **finishes** when each process holds the **complete reduction** of **chunk i**.
- ▶ At this point **each process** holds a part of the **end result**.



[<https://towardsdatascience.com/visual-intuition-on-ring-allreduce-for-distributed-deep-learning-d1f34b4911da>]

## AllReduce Implementation - Ring-AllReduce (6/6)

- ▶ The **share-only** step is the same process of sharing the data in a ring-like fashion **without** applying the reduce operation.

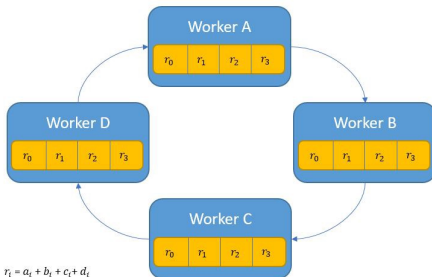


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# AllReduce Implementation - Ring-AllReduce (6/6)

- ▶ The **share-only** step is the same process of sharing the data in a ring-like fashion **without applying the reduce operation**.
- ▶ This **consolidates the result of each chunk in every process**.



[<https://towardsdatascience.com/visual-intuition-on-ring-allreduce-for-distributed-deep-learning-d1f34b4911da>]



## Master-Worker AllReduce vs. Ring-AllReduce

- ▶  $N$ : number of elements,  $m$ : number of processes



## Master-Worker AllReduce vs. Ring-AllReduce

- ▶  $N$ : number of elements,  $m$ : number of processes
- ▶ Master-Worker AllReduce



## Master-Worker AllReduce vs. Ring-AllReduce

- ▶  $N$ : number of elements,  $m$ : number of processes
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- ▶ Ring-AllReduce
  - In the share-reduce step each process sends  $\frac{N}{m}$  elements, and it does it  $m - 1$  times:  $\frac{N}{m} \times (m - 1)$  messages.





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# Communication Synchronization and Frequency



# Synchronization

- ▶ **When** to **synchronize** the **parameters** among the **parallel workers**?



## Communication Synchronization (1/2)

- ▶ Synchronizing the model replicas in data-parallel training requires communication
  - between workers, in allreduce
  - between workers and parameter servers, in the centralized architecture



## Communication Synchronization (1/2)

- ▶ Synchronizing the model replicas in data-parallel training requires communication
  - between workers, in allreduce
  - between workers and parameter servers, in the centralized architecture
- ▶ The communication synchronization decides how frequently all local models are synchronized with others.



## Communication Synchronization (2/2)

- ▶ It will influence:
  - The communication **traffic**
  - The **performance**
  - The **convergence** of model training



## Communication Synchronization (2/2)

- ▶ It will influence:
  - The communication **traffic**
  - The **performance**
  - The **convergence** of model training
- ▶ There is a **trade-off** between the communication **traffic** and the **convergence**.





# Reducing Synchronization Overhead

- ▶ Two directions for improvement:



# Reducing Synchronization Overhead

- ▶ Two directions for improvement:
  1. To **relax** the **synchronization** among all workers.



# Reducing Synchronization Overhead

- ▶ Two directions for improvement:
  1. To **relax** the **synchronization** among all workers.
  2. The **frequency of communication** can be **reduced** by more computation in one iteration.

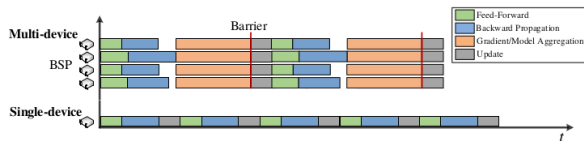


# Communication Synchronization Models

- ▶ Synchronous
- ▶ Stale-synchronous
- ▶ Asynchronous
- ▶ Local SGD

# Communication Synchronization - Synchronous

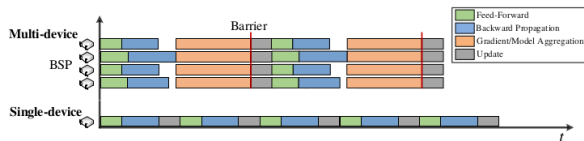
- ▶ After each **iteration**, the workers **synchronize** their parameter updates.



[Tang et al., Communication-Efficient Distributed Deep Learning: A Comprehensive Survey, 2020]

## Communication Synchronization - Synchronous

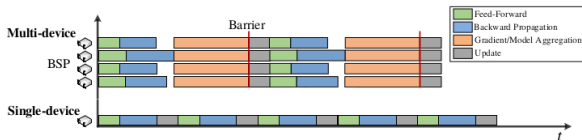
- ▶ After each **iteration**, the workers **synchronize** their parameter updates.
- ▶ Every worker must **wait** for **all workers** to **finish the transmission** of all parameters in the current iteration, before the **next training**.



[Tang et al., Communication-Efficient Distributed Deep Learning: A Comprehensive Survey, 2020]

# Communication Synchronization - Synchronous

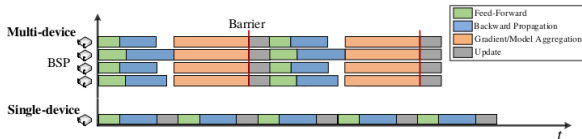
- ▶ After each **iteration**, the workers **synchronize** their parameter updates.
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- ▶ **Stragglers** can influence the overall system **throughput**.



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- ▶ Every worker must **wait** for **all workers** to **finish the transmission** of all parameters in the current iteration, before the **next training**.
- ▶ **Stragglers** can influence the overall system **throughput**.
- ▶ High **communication** cost that **limits** the system **scalability**.

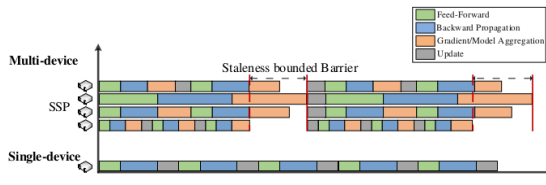


[Tang et al., Communication-Efficient Distributed Deep Learning: A Comprehensive Survey, 2020]



# Communication Synchronization - Stale Synchronous (1/2)

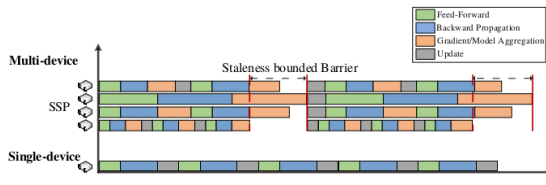
- ▶ Alleviate the straggler problem without losing synchronization.



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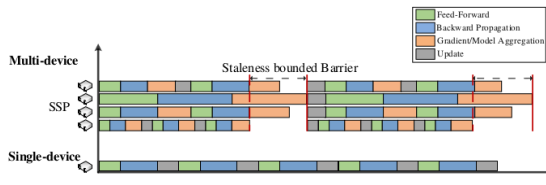
- ▶ Alleviate the straggler problem without losing synchronization.
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[Tang et al., Communication-Efficient Distributed Deep Learning: A Comprehensive Survey, 2020]

## Communication Synchronization - Stale Synchronous (1/2)

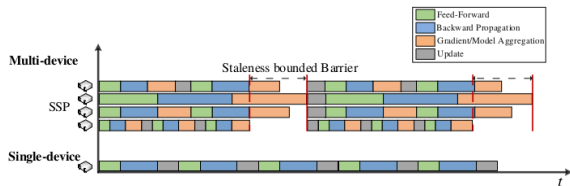
- ▶ Alleviate the straggler problem without losing synchronization.
- ▶ The faster workers to do more updates than the slower workers to reduce the waiting time of the faster workers.
- ▶ Staleness bounded barrier to limit the iteration gap between the fastest worker and the slowest worker.



[Tang et al., Communication-Efficient Distributed Deep Learning: A Comprehensive Survey, 2020]

## Communication Synchronization - Stale Synchronous (2/2)

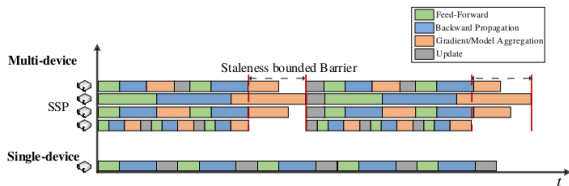
- ▶ For a maximum staleness bound  $s$ , the update formula of worker  $i$  at iteration  $t + 1$ :
- ▶ 
$$\mathbf{w}_{i,t+1} := \mathbf{w}_0 - \eta \left( \sum_{k=1}^t \sum_{j=1}^n \mathbf{G}_{j,k} + \sum_{k=t-s}^t \mathbf{G}_{i,k} + \sum_{(j,k) \in \mathcal{S}_{i,t+1}} \mathbf{G}_{j,k} \right)$$



[Tang et al., Communication-Efficient Distributed Deep Learning: A Comprehensive Survey, 2020]

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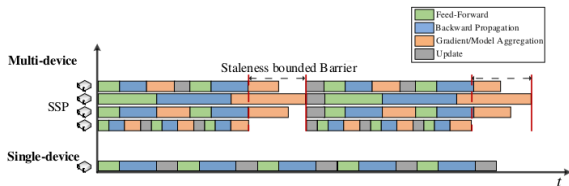
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- ▶ The update has three parts:



[Tang et al., Communication-Efficient Distributed Deep Learning: A Comprehensive Survey, 2020]

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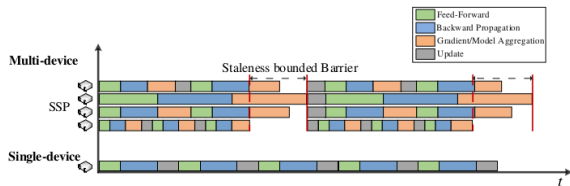
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[Tang et al., Communication-Efficient Distributed Deep Learning: A Comprehensive Survey, 2020]

## Communication Synchronization - Stale Synchronous (2/2)

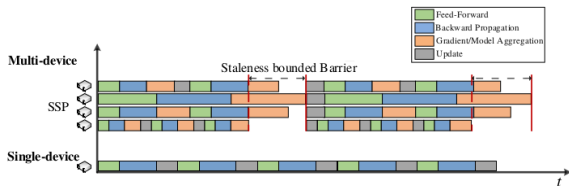
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  1. **Guaranteed pre-window updates** from clock 1 to  $t$  over all workers.
  2. **Guaranteed read-my-writes in-window updates** made by the querying worker  $i$ .



[Tang et al., Communication-Efficient Distributed Deep Learning: A Comprehensive Survey, 2020]

# Communication Synchronization - Stale Synchronous (2/2)

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  2. **Guaranteed read-my-writes in-window updates** made by the querying worker  $i$ .
  3. **Best-effort in-window updates**.  $\mathcal{S}_{i,t+1}$  is some subset of the updates from other workers during period  $[t - s]$ .

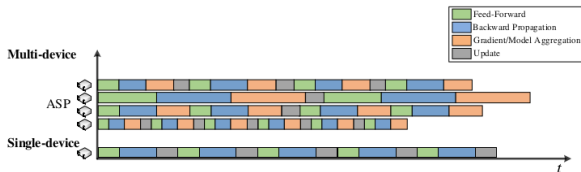


[Tang et al., Communication-Efficient Distributed Deep Learning: A Comprehensive Survey, 2020]



# Communication Synchronization - Asynchronous (1/2)

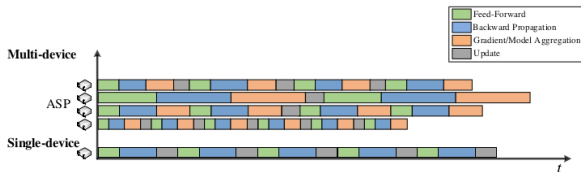
- It completely eliminates the synchronization.



[Tang et al., Communication-Efficient Distributed Deep Learning: A Comprehensive Survey, 2020]

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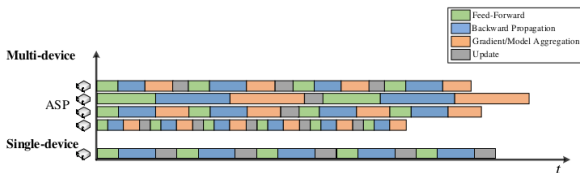
- ▶ It completely eliminates the synchronization.
- ▶ Each work transmits its gradients to the PS after it calculates the gradients.



[Tang et al., Communication-Efficient Distributed Deep Learning: A Comprehensive Survey, 2020]

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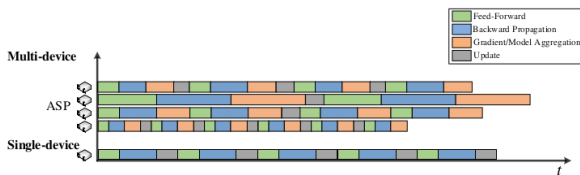
- ▶ It completely **eliminates the synchronization**.
- ▶ Each work **transmits its gradients** to the PS **after it calculates the gradients**.
- ▶ The PS updates the global model **without waiting** for the other workers.



[Tang et al., Communication-Efficient Distributed Deep Learning: A Comprehensive Survey, 2020]

## Communication Synchronization - Asynchronous (2/2)

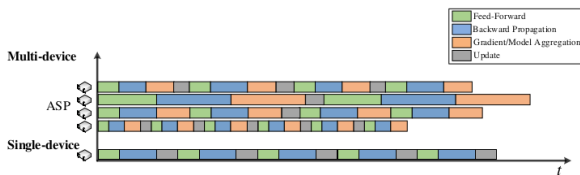
►  $\mathbf{w}_{t+1} := \mathbf{w}_t - \eta \sum_{i=1}^n \mathbf{G}_{i,t-\tau_{k,i}}$



[Tang et al., Communication-Efficient Distributed Deep Learning: A Comprehensive Survey, 2020]

# Communication Synchronization - Asynchronous (2/2)

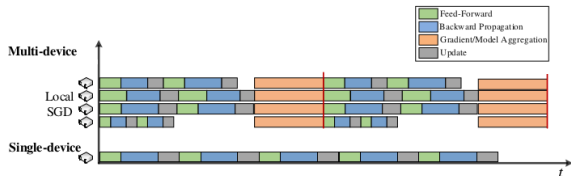
- ▶  $\mathbf{w}_{t+1} := \mathbf{w}_t - \eta \sum_{i=1}^n \mathbf{G}_{i,t-\tau_{k,i}}$
- ▶  $\tau_{k,i}$  is the time delay between the moment when worker  $i$  calculates the gradient at the current iteration.



[Tang et al., Communication-Efficient Distributed Deep Learning: A Comprehensive Survey, 2020]

## Communication Synchronization - Local SGD

- ▶ All workers run several iterations, and then averages all local models into the newest global model.

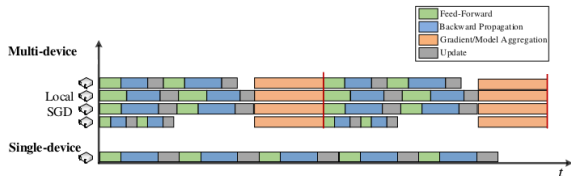


[Tang et al., Communication-Efficient Distributed Deep Learning: A Comprehensive Survey, 2020]

# Communication Synchronization - Local SGD

- ▶ All workers run several iterations, and then averages all local models into the newest global model.
- ▶ If  $\mathcal{I}_T$  represents the synchronization timestamps, then:

$$\mathbf{w}_{i,t+1} = \begin{cases} \mathbf{w}_{i,t} - \eta \mathbf{G}_{i,t} & \text{if } t + 1 \notin \mathcal{I}_T \\ \mathbf{w}_{i,t} - \eta \frac{1}{n} \sum_{i=1}^n \mathbf{G}_{i,t} & \text{if } t + 1 \in \mathcal{I}_T \end{cases}$$



[Tang et al., Communication-Efficient Distributed Deep Learning: A Comprehensive Survey, 2020]



# Communication Compression





# Communication Compression

- ▶ Reduce the communication traffic with **little impact** on the model convergence.



## Communication Compression

- ▶ Reduce the communication traffic with little impact on the model convergence.
- ▶ Compress the exchanged gradients or models before transmitting across the network.



# Communication Compression

- ▶ Reduce the communication traffic with little impact on the model convergence.
- ▶ Compress the exchanged gradients or models before transmitting across the network.
- ▶ Quantization

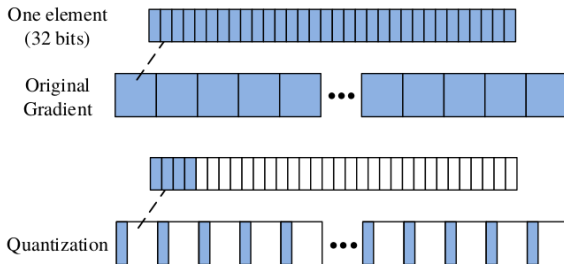


# Communication Compression

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- ▶ Quantization
- ▶ Sparsification

# Communication Compression - Quantization

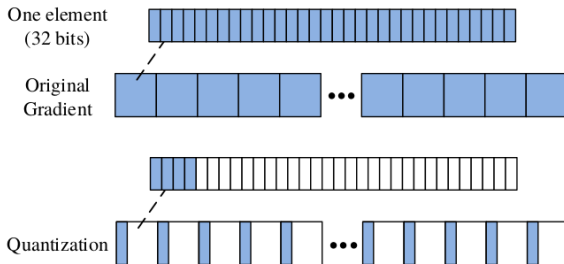
- ▶ Using **lower bits** to **represent the data**.



[Tang et al., Communication-Efficient Distributed Deep Learning: A Comprehensive Survey, 2020]

# Communication Compression - Quantization

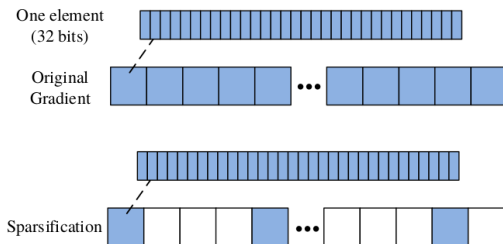
- ▶ Using **lower bits** to **represent the data**.
- ▶ The gradients are of **low precision**.



[Tang et al., Communication-Efficient Distributed Deep Learning: A Comprehensive Survey, 2020]

# Communication Compression - Sparsification

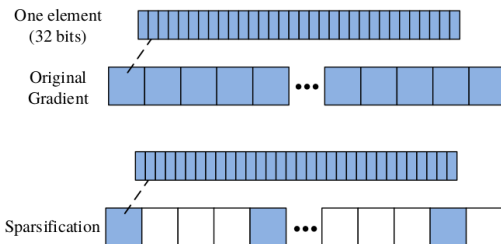
- ▶ Reducing the number of elements that are transmitted at each iteration.



[Tang et al., Communication-Efficient Distributed Deep Learning: A Comprehensive Survey, 2020]

# Communication Compression - Sparsification

- ▶ Reducing the **number of elements** that are transmitted at each iteration.
- ▶ Only **significant gradients** are required to **update the model parameter** to **guarantee the convergence** of the training.

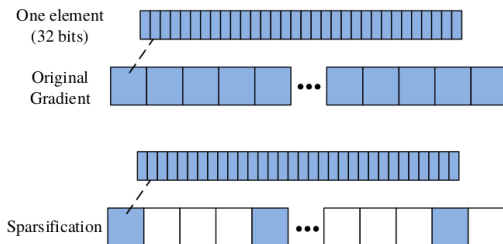


[Tang et al., Communication-Efficient Distributed Deep Learning: A Comprehensive Survey, 2020]



# Communication Compression - Sparsification

- ▶ Reducing the **number of elements** that are transmitted at each iteration.
- ▶ Only **significant gradients** are required to **update the model parameter** to **guarantee the convergence** of the training.
- ▶ E.g., the **zero-valued** elements are no need to transmit.



[Tang et al., Communication-Efficient Distributed Deep Learning: A Comprehensive Survey, 2020]



# Parallelism of Computations and Communications



## Parallelism of Computations and Communications (1/3)

- ▶ The layer-wise structure of deep models makes it possible to **parallel** the **communi-** **cation** and **computing** tasks.

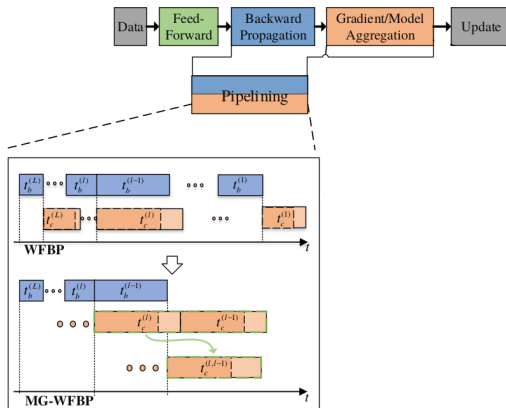


## Parallelism of Computations and Communications (1/3)

- ▶ The layer-wise structure of deep models makes it possible to **parallel** the communication and computing tasks.
- ▶ **Optimizing** the order of computation and communication such that the communication cost can be **minimized**

# Parallelism of Computations and Communications (2/3)

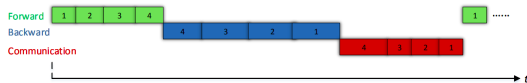
- ▶ Wait-free backward propagation (WFBP)
- ▶ Merged-gradient WFBP (MG-WFBP)



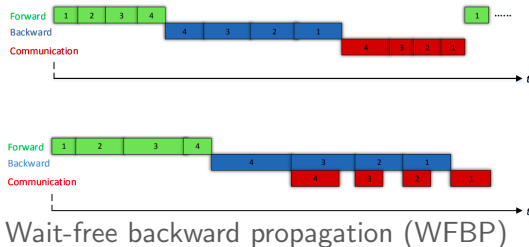
[Tang et al., Communication-Efficient Distributed Deep Learning: A Comprehensive Survey, 2020]



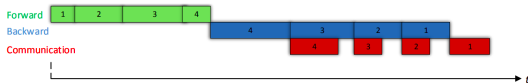
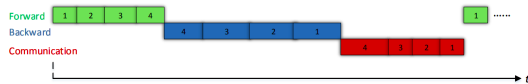
# Parallelism of Computations and Communications (3/3)



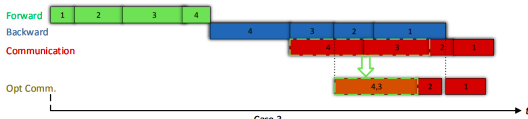
# Parallelism of Computations and Communications (3/3)



# Parallelism of Computations and Communications (3/3)



Wait-free backward propagation (WFBP)



Merged-gradient WFBP (MG-WFBP)

[shi et al., MG-WFBP: Efficient Data Communication for Distributed Synchronous SGD Algorithms, 2018]

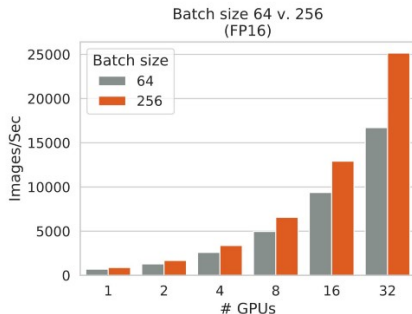




# Distributed SGD and Batch Size

## Batch Size vs. Number of GPUs

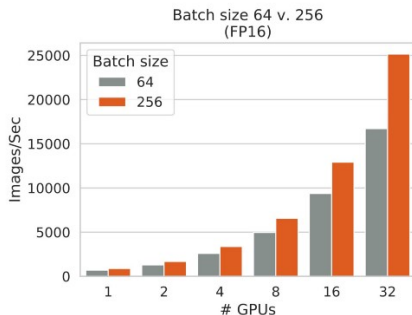
$$\triangleright \mathbf{w} \leftarrow \mathbf{w} - \eta \frac{1}{|\beta|} \sum_{\mathbf{x} \in \beta} \nabla l(\mathbf{x}, \mathbf{w})$$



[<https://medium.com/@emwatz/lessons-for-improving-training-performance-part-1-b5efd0f0dcea>]

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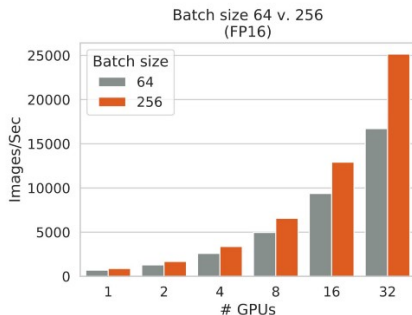
- ▶  $\mathbf{w} \leftarrow \mathbf{w} - \eta \frac{1}{|\beta|} \sum_{\mathbf{x} \in \beta} \nabla l(\mathbf{x}, \mathbf{w})$
- ▶ The more samples processed during each batch, the faster a training job will complete.



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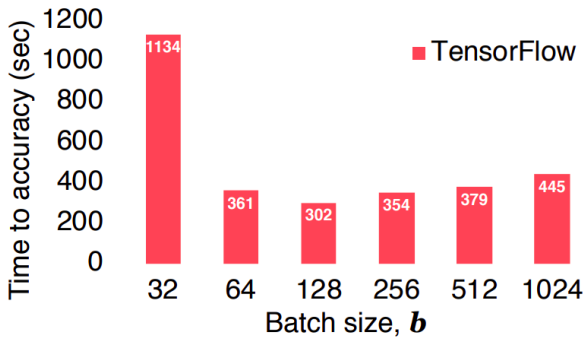
- ▶  $\mathbf{w} \leftarrow \mathbf{w} - \eta \frac{1}{|\beta|} \sum_{\mathbf{x} \in \beta} \nabla l(\mathbf{x}, \mathbf{w})$
- ▶ The **more samples** processed during each batch, the **faster** a **training job** will complete.
- ▶ E.g., ImageNet + ResNet-50



[<https://medium.com/@emwatz/lessons-for-improving-training-performance-part-1-b5efd0f0dcea>]

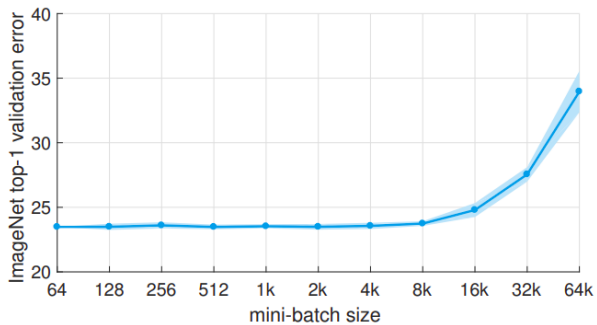
## Batch Size vs. Time to Accuracy

- ▶ ResNet-32 on Titan X GPU



[Peter Pietzuch - Imperial College London]

## Batch Size vs. Validation Error



[Goyal et al., Accurate, Large Minibatch SGD: Training ImageNet in 1 Hour, 2018]



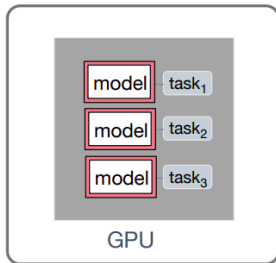
# CROSSBOW: Scaling Deep Learning with Small Batch Sizes on Multi-GPU Servers



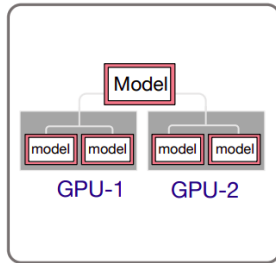
- ▶ How to design a deep learning system that **scales training** with **multiple GPUs**, even when the preferred **batch size is small**?



**(1) How to increase efficiency with small batches?**



**(2) How to synchronise model replicas?**



[Peter Pietzuch - Imperial College London]

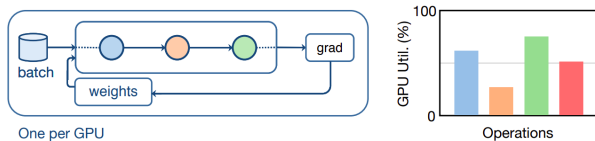


## Problem: Small Batches

- ▶ Small batch sizes **underutilise** GPUs.

## Problem: Small Batches

- ▶ Small batch sizes **underutilise** GPUs.
- ▶ One batch per GPU: **not enough data** and instruction parallelism for every operator.

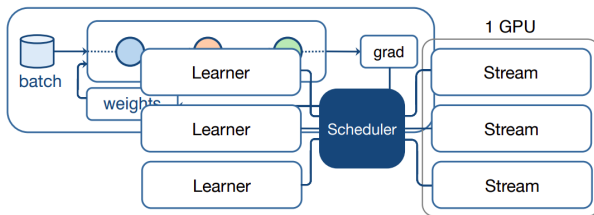


One per GPU

[Peter Pietzuch - Imperial College London]

## Idea: Multiple Replicas Per GPU

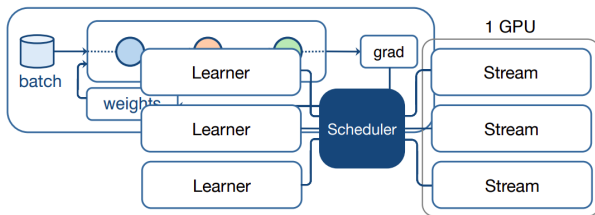
- ▶ Train **multiple model replicas** per GPU.
- ▶ A **learner** is an entity that trains a **single model replica** **independently** with a given batch size.



[Peter Pietzuch - Imperial College London]

# Idea: Multiple Replicas Per GPU

- ▶ Train **multiple model replicas** per GPU.
- ▶ A **learner** is an entity that trains a **single model replica** **independently** with a given batch size.

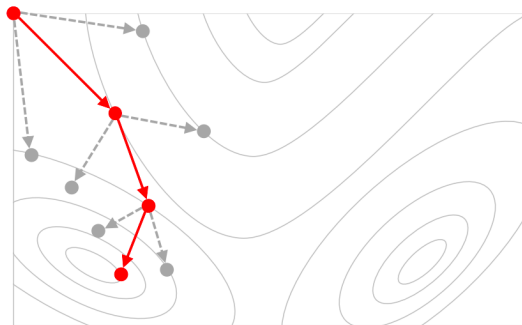


[Peter Pietzuch - Imperial College London]

- ▶ But, now we must **synchronise** a **large number** of **model replicas**.

## Problem: Similar Starting Point

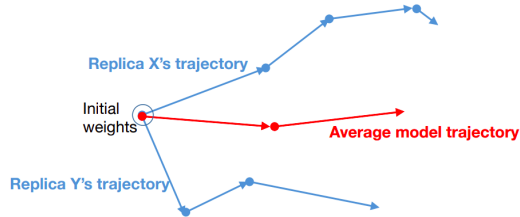
- ▶ All learners always **start** from the **same point**.
- ▶ **Limited exploration** of parameter space.



[Peter Pietzuch - Imperial College London]

# Idea: Independent Replicas

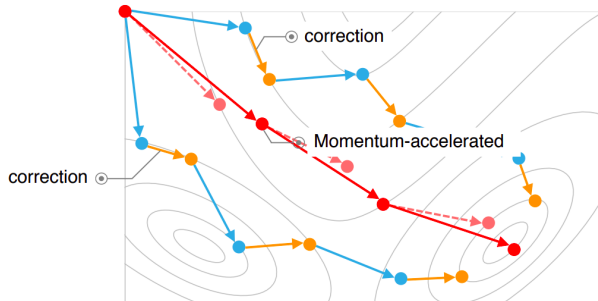
- ▶ Maintain independent model replicas.
- ▶ Increased exploration of space through parallelism.
- ▶ Each model replica uses small batch size.



[Peter Pietzuch - Imperial College London]

# Crossbow: Synchronous Model Averaging

- ▶ Allow learners to **diverge**, but **correct trajectories** based on **average model**.
- ▶ Accelerate average model trajectory with **momentum** to find minima faster.

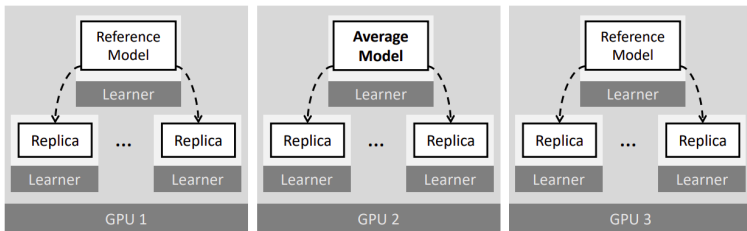


[Peter Pietzuch - Imperial College London]



# GPUs with Synchronous Model Averaging

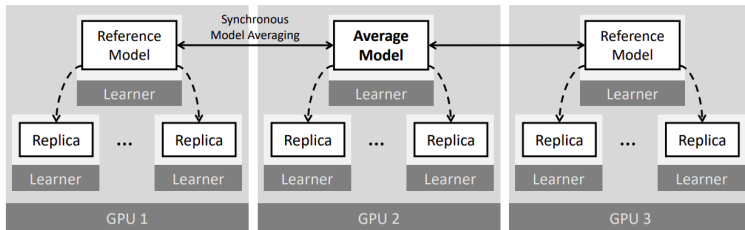
- ▶ Synchronously apply corrections to **model replicas**.



[Peter Pietzuch - Imperial College London]

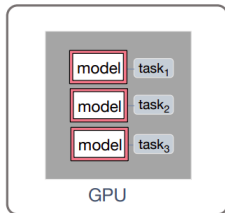
## GPUs with Synchronous Model Averaging

- ▶ Ensures consistent view of average model.
- ▶ Takes GPU bandwidth into account during synchronisation.



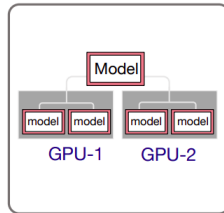
[Peter Pietzuch - Imperial College London]

**(1) How to increase efficiency with small batches?**



Train multiple model replicas per GPU

**(2) How to synchronise model replicas?**



Use synchronous model averaging

[Peter Pietzuch - Imperial College London]

# Summary



## Summary

- ▶ Data-parallel
- ▶ The aggregation algorithm
- ▶ Communication synchronization
- ▶ Communication compression
- ▶ Parallelism of computations and communications
- ▶ Batch Size



## Reference

- ▶ Tang et al., Communication-Efficient Distributed Deep Learning: A Comprehensive Survey, 2020
- ▶ P. Goyal et al., Accurate, large minibatch sgd: Training imagenet in 1 hour, 2017
- ▶ C. Shallue et al., Measuring the effects of data parallelism on neural network training, 2018
- ▶ A. Kolios et al. CROSSBOW: scaling deep learning with small batch sizes on multi-gpu servers, 2019

Questions?