



# Distributed Roubust Learning

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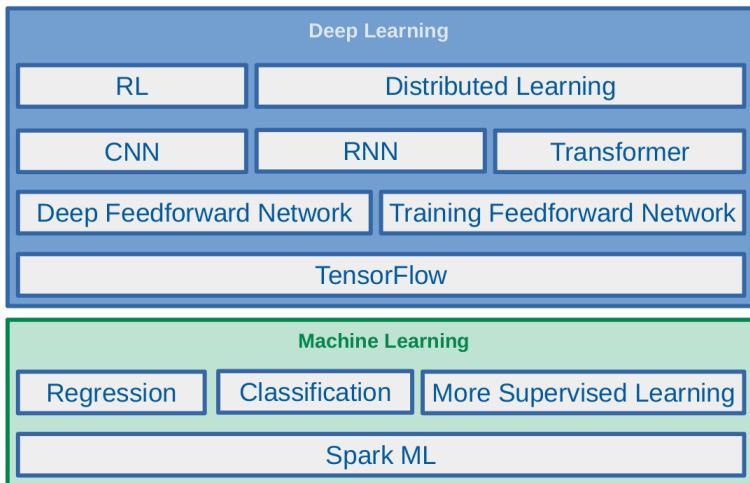


## The Course Web Page

`https://id2223kth.github.io`  
`https://tinyurl.com/6s5jy46a`

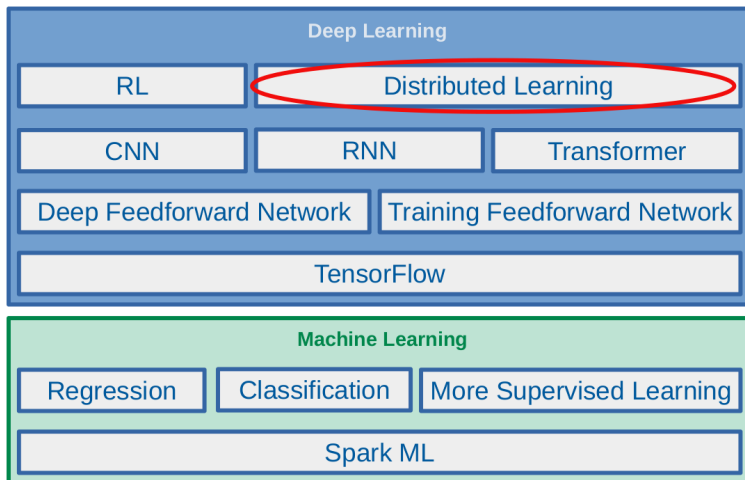


# Where Are We?





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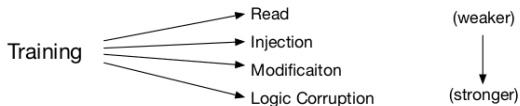
# Adversarial Goals

- ▶ Confidentiality and privacy
  - Confidentiality of the **model** or the **data**.
- ▶ Integrity
  - Integrity of the **predictions**
- ▶ Availability
  - Availability of the **system** deploying machine learning



# Adversarial Capabilities for Integrity Attacks

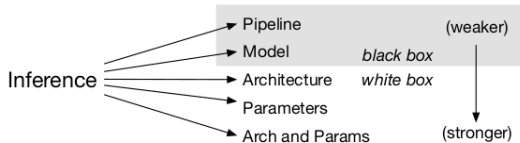
## ▶ Training phase



[Papernot et al., SoK: Security and Privacy in Machine Learning, 2018]

## ▶ Inference phase

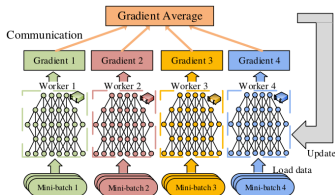
- White box
- Black box



[Papernot et al., SoK: Security and Privacy in Machine Learning, 2018]

## Our Focus and Goal

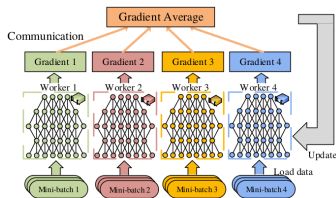
- ▶ Data parallelization
- ▶ Each worker is prone to **adversarial attack**.
- ▶ **Adversarial attacks**: some unknown subset of computing devices are **compromised and behave adversarially** (e.g., sending out malicious messages)
- ▶ Our goal: **integrity** of the model in the **training** phase



[Tang et al., Communication-Efficient Distributed Deep Learning: A Comprehensive Survey, 2020]

# Distributed Stochastic Gradient Descent (1/3)

- ▶ One **parameter server**, and  **$n$**  workers.
- ▶ Computation is divided into **synchronous rounds**.
- ▶ During round  **$t$** , the **parameter server** broadcasts its parameter vector  $w \in \mathbb{R}^d$  to all the **workers**.

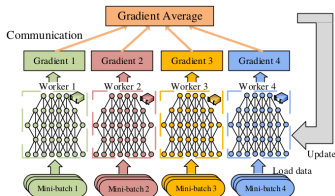


[Tang et al., Communication-Efficient Distributed Deep Learning: A Comprehensive Survey, 2020]



## Distributed Stochastic Gradient Descent (2/3)

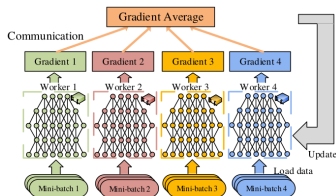
- ▶ At each round  $t$ , each **correct worker**  $i$  computes  $G_i(w_t, \beta)$ .
- ▶  $G_i(w_t, \beta)$ : the **local estimate** of the gradient of the loss function  $\nabla J(w_t)$ .
- ▶  $\beta$ : a mini-batch of **i.i.d. samples** drawn from the dataset.
- ▶  $G_i(w_t, \beta) = \frac{1}{|\beta|} \sum_{x \in \beta} \nabla l_i(w_t, x)$



[Tang et al., Communication-Efficient Distributed Deep Learning: A Comprehensive Survey, 2020]

# Distributed Stochastic Gradient Descent (3/3)

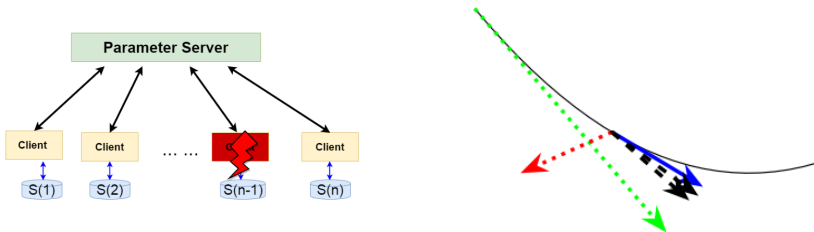
- ▶ The parameter server computes  $F(G_1, G_2, \dots, G_n)$
- ▶ **Gradient Aggregation Rule (GAR):**  $F(G_1, G_2, \dots, G_n) = \frac{1}{n} \sum_{i=1}^n G_i$
- ▶ The parameter server updates the parameter vector  $w \leftarrow w - \gamma F(G_1, G_2, \dots, G_n)$



[Tang et al., Communication-Efficient Distributed Deep Learning: A Comprehensive Survey, 2020]

# Distributed SGD with Byzantine Workers

- ▶ Among the  $n$  workers,  $f$  of them are possibly Byzantine (behaving arbitrarily).
- ▶ A Byzantine worker  $b$  proposes a vector  $G_b$  that can deviate arbitrarily from the vector it is supposed.



[El-Mhamdi et al., Fast and Secure Distributed Learning in High Dimension, 2019]



## Averaging GAR and Byzantine Workers

- ▶ Averaging GAR:  $F(G_1, G_2, \dots, G_n) = \frac{1}{n} \sum_{i=1}^n G_i$
- ▶  $w \leftarrow w - \gamma F(G_1, G_2, \dots, G_n)$
- ▶ Even a **single Byzantine** worker can **prevent convergence**.
- ▶ **Proof:** if the Byzantine worker proposes  $G_n = nU - \sum_{i=1}^{n-1} G_i$ , then  $F = U$ .

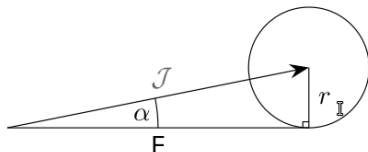


## $(\alpha, f)$ -Byzantine-Resilience (1/2)

- ▶ Assume  $n$  workers, where  $f$  of them are **Byzantine** workers.
- ▶  $\alpha \in [0, \pi/2]$  and  $f \in \{0, \dots, n\}$ .
- ▶  $(\mathbf{G}_1, \dots, \mathbf{G}_{n-f}) \in (\mathbb{R}^d)^{n-f}$  are **i.i.d.** random vectors
  - $\mathbf{G}_i \sim g$
  - $\mathbb{E}[g] = \mathcal{J}$ , where  $\mathcal{J} = \nabla J(w)$
- ▶  $(\mathbf{B}_1, \dots, \mathbf{B}_f) \in (\mathbb{R}^d)^f$  are random vectors, possibly **dependent** between them and the vectors  $(\mathbf{G}_1, \dots, \mathbf{G}_{n-f})$

## $(\alpha, f)$ -Byzantine-Resilience (2/2)

- A GAR  $\mathbf{F}$  is said to be  $(\alpha, f)$ -Byzantine-resilient if, for any  $1 \leq j_1 < \dots < j_f \leq n$ , the vector  $\mathbf{F}(\mathbf{G}_1, \dots, \mathbf{B}_1, \dots, \mathbf{B}_f, \dots, \mathbf{G}_n)$  satisfies:
1. Vector  $\mathbf{F}$  that is **not too far** from the **real gradient**  $\mathcal{J}$ , i.e.,  $\|\mathbb{E}[\mathbf{F}] - \mathcal{J}\| \leq r$ .
  2. Moments of  $\mathbf{F}$  should be **controlled** by the moments of the (correct) gradient estimator  $\mathbf{g}$ , where  $\mathbb{E}[\mathbf{g}] = \mathcal{J}$ .



[Blanchard et al., Machine Learning with Adversaries: Byzantine Tolerant Gradient Descent, 2017]



# Byzantine-Resilience GAR

- ▶ Median
- ▶ Krum
- ▶ Multi-Krum
- ▶ Brute

# Median

- ▶  $n \geq 2f + 1$
- ▶  $\text{median}(x_1, \dots, x_n) = \arg \min_{x \in \mathbb{R}} \sum_{i=1}^n |x_i - x|$
- ▶  $d$ : the gradient vectors **dimension**.

- ▶ **Geometric** median

$$F = \text{GeoMed}(G_1, \dots, G_n) = \arg \min_{G \in \mathbb{R}^d} \sum_{i=1}^n \|G_i - G\|$$

- ▶ **Marginal** median

$$F = \text{MarMed}(G_1, \dots, G_n) = \begin{pmatrix} \text{median}(G_1[1], \dots, G_n[1]) \\ \vdots \\ \text{median}(G_1[d], \dots, G_n[d]) \end{pmatrix} \quad (1)$$

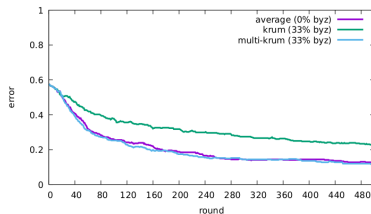




- ▶  $n \geq 2f + 3$
- ▶ Idea: to **preclude** the vectors that are **too far away**.
- ▶  $s(i) = \sum_{i \rightarrow j} \|G_i - G_j\|^2$ , the score of the worker  $i$ .
- ▶  $i \rightarrow j$  denotes that  $G_j$  belongs to the  $n - f - 2$  closest vectors to  $G_i$ .
- ▶  $F(G_1, \dots, G_n) = G_{i_*}$
- ▶  $G_{i_*}$  refers to the worker minimizing the score,  $s(i_*) \leq s(i)$  for all  $i$ .

# Multi-Krum

- ▶ **Multi-Krum** computes the **score** for each vector proposed (as in Krum).
- ▶ It selects  $m$  vectors  $G_{1*}, \dots, G_{m*}$ , which score the **best** ( $1 \leq m \leq n - f - 2$ ).
- ▶ It outputs their average  $\frac{1}{m} \sum_i G_{i*}$ .
- ▶ The cases  $m = 1$  and  $m = n$  correspond to **Krum** and **averaging**, respectively.

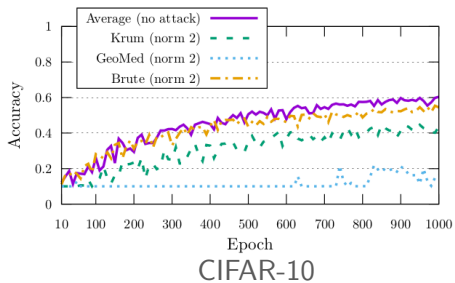
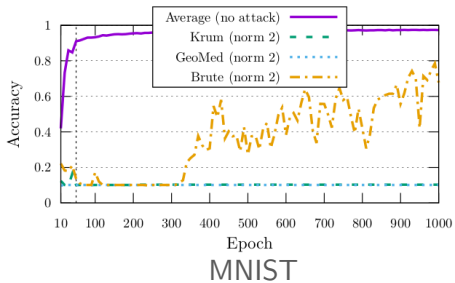


[Blanchard et al., Machine Learning with Adversaries: Byzantine Tolerant Gradient Descent, 2017]



# Brute

- ▶  $n \geq 2f + 1$
- ▶  $\mathcal{Q} = \{G_1, G_2, \dots, G_n\}$
- ▶  $\mathcal{R} = \{\mathcal{X} \mid \mathcal{X} \subset \mathcal{Q}, |\mathcal{X}| = n - f\}$ 
  - The set of all the **subsets** of  $n - f$
- ▶  $\mathcal{S} = \arg \min_{\mathcal{X} \in \mathcal{R}} (\max_{(G_i, G_j) \in \mathcal{X}^2} (\|G_i - G_j\|))$ 
  - Selects the  $n - f$  **most clumped gradients** among the submitted ones.
- ▶  $F(G_1, \dots, G_n) = \frac{1}{n-f} \sum_{G \in \mathcal{S}} G$



[El Mhamdi et al., The Hidden Vulnerability of Distributed Learning in Byzantium, 2018]



# Weak Byzantine Resilience

- ▶ **Limitation** of previous aggregation methods.
- ▶ If gradient dimension  $d \gg 1$ , then the distance function between two vectors  $\|X - Y\|_p$ , cannot distinguish these two cases:
  - ▶ 1. Does  $X$  and  $Y$  **disagree** a **bit** on each coordinate?
  - ▶ 2. Does  $X$  and  $Y$  **disagree** a **lot** on **only one**?



## Strong Byzantine Resilience

- ▶ Ensuring **convergence** (as in **weak Byzantine resilience** functions).
- ▶ Ensures that **each coordinate** is agreed on by a **majority of vectors** that were selected by a **Byzantine resilient** aggregation rule **A**.
- ▶ **A** can be Brute, Krum, Median, etc.
- ▶ **Bulyan** is a strong Byzantine-resilience algorithm.



# The Hidden Vulnerability of Distributed Learning in Byzantium



## Bulyan - Step One (1/2)

- ▶  $n \geq 4f + 3$
- ▶ A **two step** process.
- ▶ The first one is to **recursively** use **A** to select  $\theta = n - 2f$  gradients:
  1. With **A**, choose, among the proposed vectors, the closest one to **A**'s output (for Krum this would be the exact output of **A**).
  2. Remove the chosen gradient from the **received set** and add it to the **selection set S**.
  3. Loop back to step 1 if  $|S| < \theta$ .





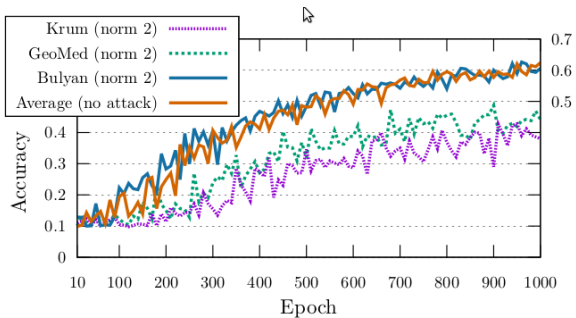
## Bulyan - Step One (2/2)

- ▶  $\theta = n - 2f \geq 2f + 3$ , thus  $S = (S_1, \dots, S_\theta)$  contains a majority of non-Byzantine gradients.
- ▶ For each  $i \in [1..d]$ , the median of the  $\theta$  coordinates  $i$  of the selected gradients is always bounded by coordinates from non-Byzantine submissions.



## Bulyan - Step Two

- ▶ The second step is to generate the resulting gradient  $\mathbf{F} = (F[1], \dots, F[d])$ .
- ▶  $\forall i \in [1..d], F[i] = \frac{1}{\beta} \sum_{\mathbf{x} \in M[i]} \mathbf{x}[i]$
- ▶  $\beta = \theta - 2f \geq 3$
- ▶  $M[i] = \arg \min_{R \subseteq S, |R|=\beta} (\sum_{\mathbf{x} \in R} |\mathbf{x}[i] - \text{median}[i]|)$
- ▶  $\text{median}[i] = \arg \min_{m=Y[i], Y \subseteq S} (\sum_{Z \in S} |Z[i] - m|)$
- ▶ Each  $i$ th coordinate of  $\mathbf{F}$  is equal to the average of the  $\beta$  closest  $i$ th coordinates to the median  $i$ th coordinate of the  $\theta$  selected gradients.



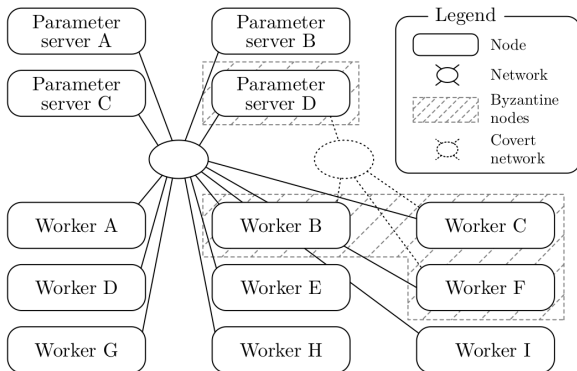
[El Mhamdi et al., The Hidden Vulnerability of Distributed Learning in Byzantium, 2018]



What if parameter servers are Byzantine?



# SGD: Decentralized Byzantine Resilience



[El Mhamdi et al., SGD: Decentralized Byzantine Resilience, 2019]



# GuanYu

- ▶ Byzantine tolerant learning algorithm that is
  1. Resilience to Byzantine workers.
  2. Resilience to Byzantine parameter servers.
- ▶ GuanYu tolerates up to  $\frac{1}{3}$  Byzantine servers and  $\frac{1}{3}$  Byzantine workers.
- ▶ GuanYu uses a GAR for aggregating workers' gradients and Median for aggregating models received from servers.



## Assumptions and Notations (1/2)

- ▶ **Asynchronous network**: the **lack of any bound** on communication delays.
- ▶ **Synchronous training**: **bulk-synchronous** training.
  - The parameter server does **not need to wait** for all the workers' gradients to make progress, and vice versa.
  - The **quorums** indicate the **number of messages to wait** before aggregating them.





## Assumptions and Notations (2/2)

- ▶  $n_{ps} \geq 3f_{ps} + 3$  the total number of parameter servers, among which  $f_{ps}$  are Byzantine.
- ▶  $n_{wr} \geq 3f_{wr} + 3$  the total number of workers, among which  $f_{wr}$  are Byzantine.
- ▶  $M$  the coordinate-wise median (used in both workers and servers).
- ▶  $F$  the GAR function (used in the servers)
- ▶  $2f_{ps} + 3 \leq q_{ps} \leq n_{ps} - f_{ps}$  the quorum used for  $M$ .
- ▶  $2f_{wr} + 3 \leq q_{wr} \leq n_{wr} - f_{wr}$  the quorum used for  $F$ .
- ▶  $d$  the dimension of the parameter space  $\mathbb{R}^d$ .



## GuanYu Algorithm - Step 1

- ▶ At each step  $t$ , each non-Byzantine server  $i$  broadcasts its current parameter vector  $w_i^t$  to every worker.
- ▶ Each non-Byzantine worker  $j$  aggregates with  $M$  the  $q_{ps}$  first received  $w^t$ .
- ▶ And computes an estimate  $G_j^t$  of the gradient at the aggregated parameters.



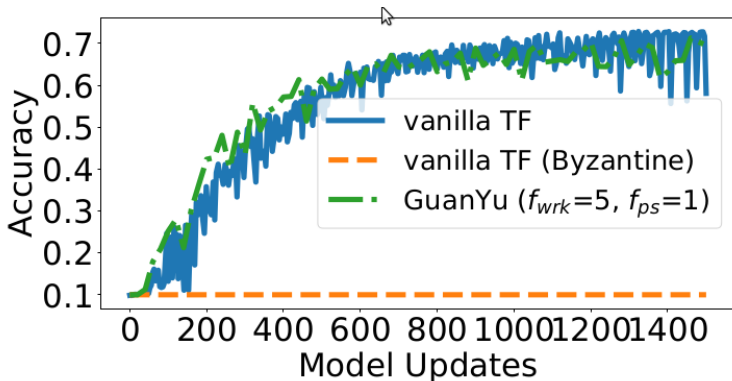
## GuanYu Algorithm - Step 2

- ▶ Each **non-Byzantine worker**  $j$  broadcasts its **computed gradient estimation**  $G_j^t$  to every **parameter server**.
- ▶ Each **non-Byzantine parameter server**  $i$  aggregates with  $F$  the  $q_{wr}$  first received  $G^t$ .
- ▶ And performs a **local parameter update** with the aggregated gradient, resulting in  $\bar{w}_i^t$ .



## GuanYu Algorithm - Step 3

- ▶ Each non-Byzantine parameter server  $i$  broadcasts  $\bar{w}_i^{t+1}$  to every other parameter servers.
- ▶ They aggregate with  $M$  the  $q_{ps}$  first received  $\bar{w}_k^{t+1}$ .
- ▶ This aggregated parameter vector is  $\bar{w}_i^{t+1}$ .



[El Mhamdi et al., SGD: Decentralized Byzantine Resilience, 2019]

# Summary



## Summary

- ▶ Integrity in data-parallel learning
- ▶ Weak Byzantine resilience
- ▶ Strong Byzantine resilience
- ▶ Byzantine parameter servers



## Reference

- ▶ Xie et al., Generalized Byzantine-tolerant SGD, 2018
- ▶ Blanchard et al., Machine Learning with Adversaries: Byzantine Tolerant Gradient Descent, 2017
- ▶ El Mhamdi et al., The Hidden Vulnerability of Distributed Learning in Byzantium, 2018
- ▶ Damaskinos et al., AGGREGATHOR: Byzantine Machine Learning via Robust Gradient Aggregation, 2019
- ▶ El Mhamdi et al., SGD: Decentralized Byzantine Resilience, 2019
- ▶ El Mhamdi et al., Fast Machine Learning with Byzantine Workers and Servers, 2019



Questions?